

SKAA 1213 - Engineering Mechanics

TOPIC 1

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What is Mechanics

- Study of bodies at rest or motion that are subjected to the action of force
 - > Rigid-body mechanics
 - Deformable-body mechanics
 - Fluid mechanics
- Rigid body mechanics
 - Statics equilibrium of bodies either at rest or moving at a constant velocity
 - Dynamics bodies in accelerated motion







Idealisations

- help to simplify application of the theory.
- Particle has mass but the size can be neglected. The geometry is not involved in the analysis.
- Rigid Body consider as a combination of large number of particles in which all the particles remained at a fixed distance from one another before and after applying a load.
- Concentrated Force represents the effect of a loading which is assumed to act at a point on a body.



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Scalar and Vectors Quantities

Most physical quantities in mechanics can be expressed mathematically by means of scalar and vector quantities.

- **Scalar** quantity that has magnitude but not direction. eg. **Mass** (*m*), **volume** (*V*), **length** (*l*)
- Vector quantity that has both a magnitude and a direction.
 eg. Force (F), moment (M), position (r)

A vector is represented graphically by an **arrow**;



Newton's Law of Motion

Rigid body mechanics is formulated on the basis of Newton's three laws of motion.

First Law: A particle originally at rest, or moving in a straight line with constant velocity, will remain in this state provided the particle is not subjected to an unbalanced force

Second Law: A particle acted upon by an unbalanced force **F** experiences an acceleration **a** that has the same direction as the force and a magnitude that is directly proportional to the force.

F = m**a**

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Third Law: the mutual force of action and reaction between two particles are equal, opposite, and collinear.

F₁ F₂ F₃ Equilibrium



Accelerated motion



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