

# MODULE 5

## SORTING

### DATA STRUCTURE AND ALGORITHMS

FACULTY OF COMPUTING UNIVERSITI TEKNOLOGI MALAYSIA

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#### **MODULE 5: SORTING**

#### **OBJECTIVES FOR STUDENTS**

- 1. To describe the purpose of sorting technique as operations on data structure.
- 2. To write source codes for the implementation of simple sort algorithms : Bubble Sort, Insertion Sort and Selection Sort
- 3. To write source codes for the implementation of divide and conquer sorting algorithms : Merge Sort and Quick Sort.
- 4. To identify the efficiency of the sorting algorithms and determine the suitable sorting techniques for certain problem.

#### **KEY CONCEPT**

#### **1.0 INTRODUCTION TO SORTING**

- 1.1. **Sorting definition -** A process in which data in a list are organized in certain order; either ascending or descending order.
- 1.2. Advantages of sorted lists:
  - i. Easier to understand and analyze data collection.
  - ii. Searching process will be much faster.
  - Sorting Example :
    - i. Sorted in Ascending order: phone directory and dictionary
    - ii. Sorted in Descending order; number of scores/points earned by every team in a competition. The winner gets the highest score.

#### 1.3. Sorting Algorithms Categories:

- i. An internal sort
  - Requires that the collection of data fit entirely in the computer's main memory. Suitable to sort a small size of list.
- ii. An external sort
  - The collection of data will not fit in the computer's main memory all at once, but must reside in secondary storage. Suitable to sort large





size of data.

- 1.4. Types of lists to be sorted:
  - List of simple data types, such as integers, char or strings
  - Examples: list of numbers (**int** type) or list of book titles (**string** type) as shown in the figure below:

List of student's age (int)				
22				
28				
18				
23				

19

List of Book Titles (string) Struktur Data Learning English

9
Mathematics for
Kids
Effective
Communication
Learn C++

1.5. Sorting list of records

- Each record contains a field called the **key**.
- Record key field that become the identifier to the record.
- For sorting purposes, the records will be sorted based on the sorting key, which is part of the data item that we consider when sorting a data collection.
- Example: A list that contains student's information

	Sorting key The list can be sorted either by student's name, matrix number or CPA.								
	Indeks	Student Name	Matrix Number	СРА					
ſ	[0]	Hisham	A5021	3.09					
Listof	[1]	Zainal	A1051	2.55					
List of records	[2]	Maria	A2000	3.60					
	[3]	Adam	A5501	3.00					
	[4]	Zahid	A2233	2.95					

#### **2.0 SORTING PROCESS**

2.1. Two main activities in the sorting process:i. Compare: compare between two elements. If they are not in correct





order, then

ii. **Swap:** Change the position of the elements in order to get the right order.

#### 2.2. The **efficiency** of sorting algorithm is measured based on :

- the number of comparisons and
- the number of swapping between elements
- 2.3. The sorting efficiency is measured based on the execution time of the algorithm when tested using sample **cases** of data as follows:
  - Worst-case analysis considers the maximum amount of work an algorithm will require on a problem of a given size. (Data is totally unsorted).
  - **Best-case analysis** considers the minimum amount of work an algorithm will require on a problem of a given size. (Data is almost sorted).
  - Average-case analysis considers the expected amount of work that an algorithm will require on a problem of a given size.

#### **3.0 SORTING ALGORITHMS**

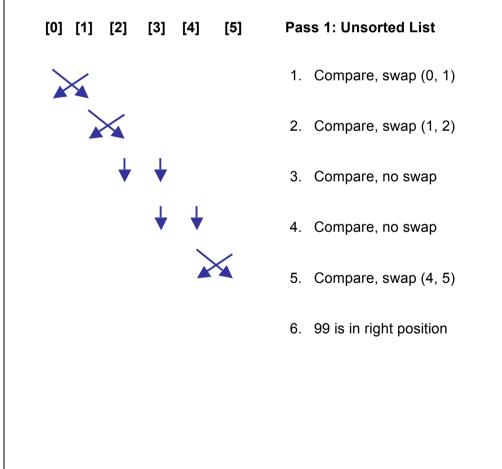
- 3.1. There are several sorting algorithms. In this module, two **strategies** of sorting techniques will be discussed in detail. They are:
  - i. Quadratic Sorting Algorithms
  - ii. Divide and Conquer Sorting Algorithms
- 3.2. **Quadratic** Sorting Algorithms work straight-forward and sorting methods is usually people think of sorting things in general. The quadratic sorting algorithms are not very fast and with quadratic efficiency.
- 3.3. Three quadratic sorting algorithms are:
  - i. Bubble Sort
  - ii. Insertion Sort
  - iii. Selection Sort
- 3.4. Divide and Conquer Sorting Algorithms strategy solves a problem by :
  - i. Breaking into sub problems that are themselves smaller instances of the same type of problem.
  - ii. Recursively solving these sub problems.
  - iii. Appropriately combining their answers.
- 3.5. Two types of sorting algorithms which are based on this divide and conquer algorithm :
  - i. Merge Sort
  - ii. Quick Sort

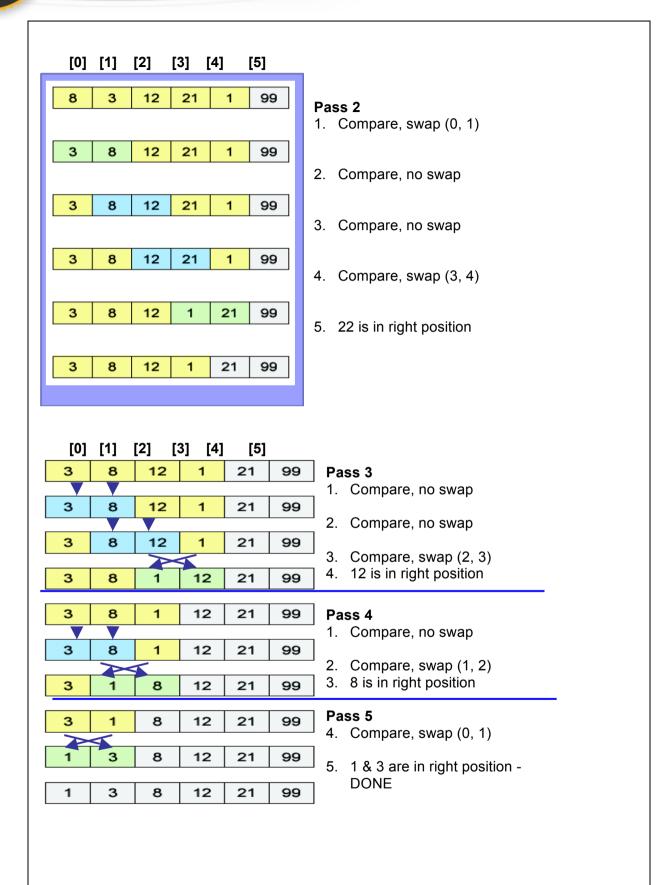




#### 4.0 BUBBLE SORT

- 4.1. Bubble sort is a simple sorting technique in which will arrange the elements of the list by comparing each pair of adjacent items and swapping them if they are in the wrong order.
- 4.2. To sort an array of record with bubble sort, it works by taking multiple passes over the array with the following main activities
  - i. Compare adjacent elements in the list
  - ii. **Exchange** the elements if they are out of order
  - iii. Each pass **moves the largest** (or smallest) elements to the end of the array
  - iv. **Repeating** this process eventually sorts the array into ascending (or descending) order.
- 4.3. Bubble sort is a quadratic algorithm  $O(n^2)$ . The algorithm only suitable to sort array with small size of data.
- 4.4. Example of Bubble Sort operation with list of 8 elements.



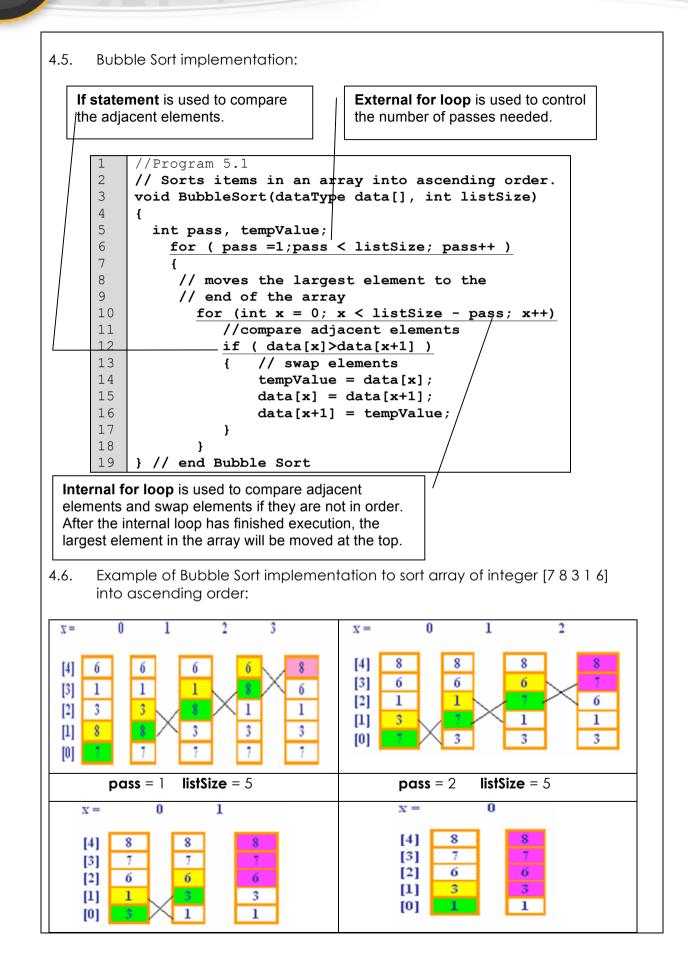


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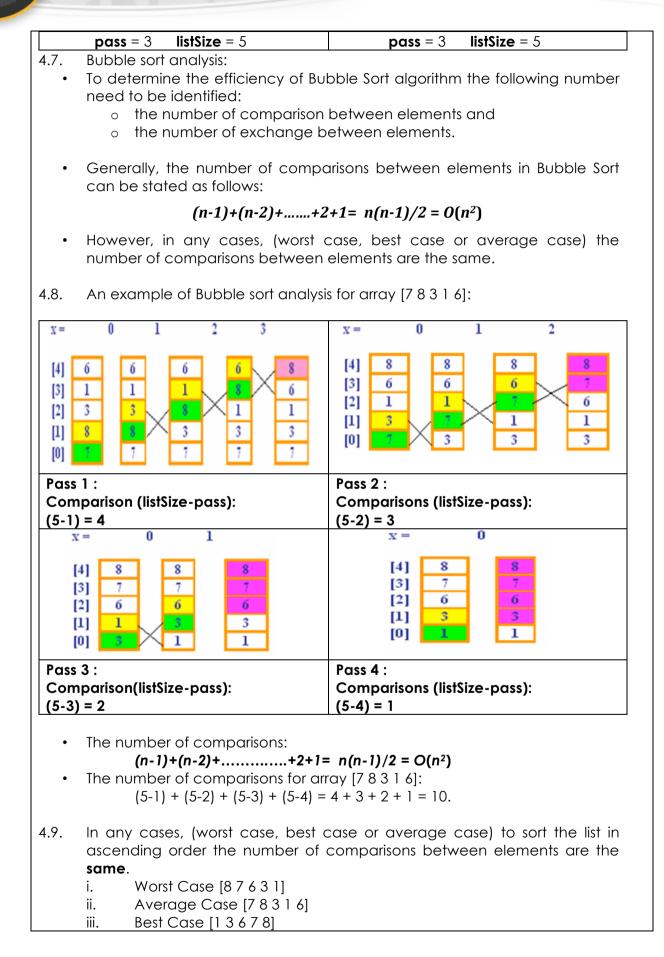








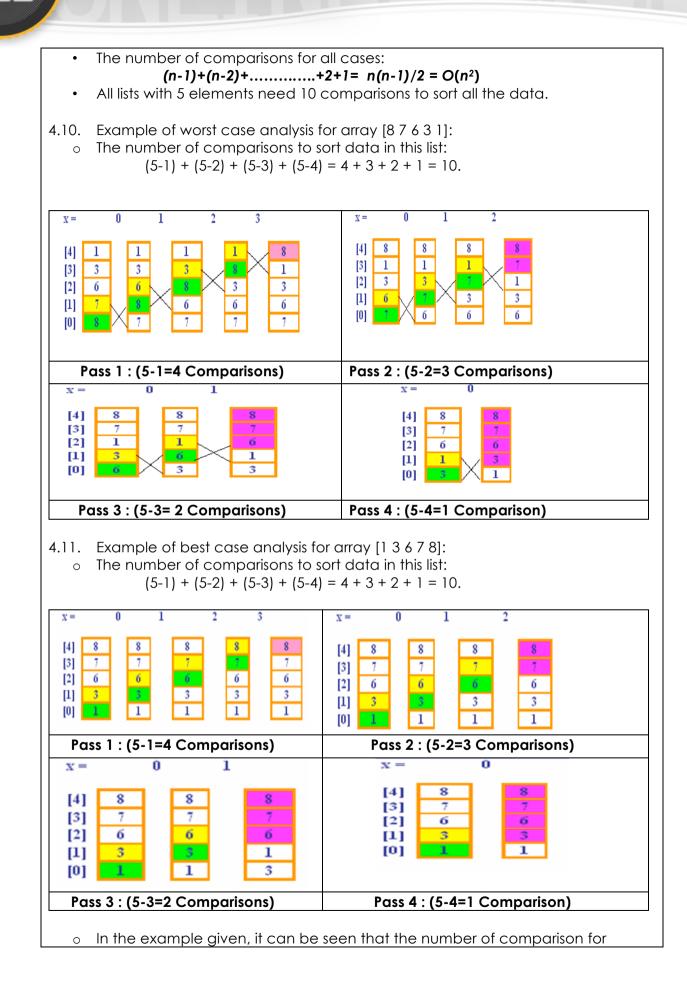








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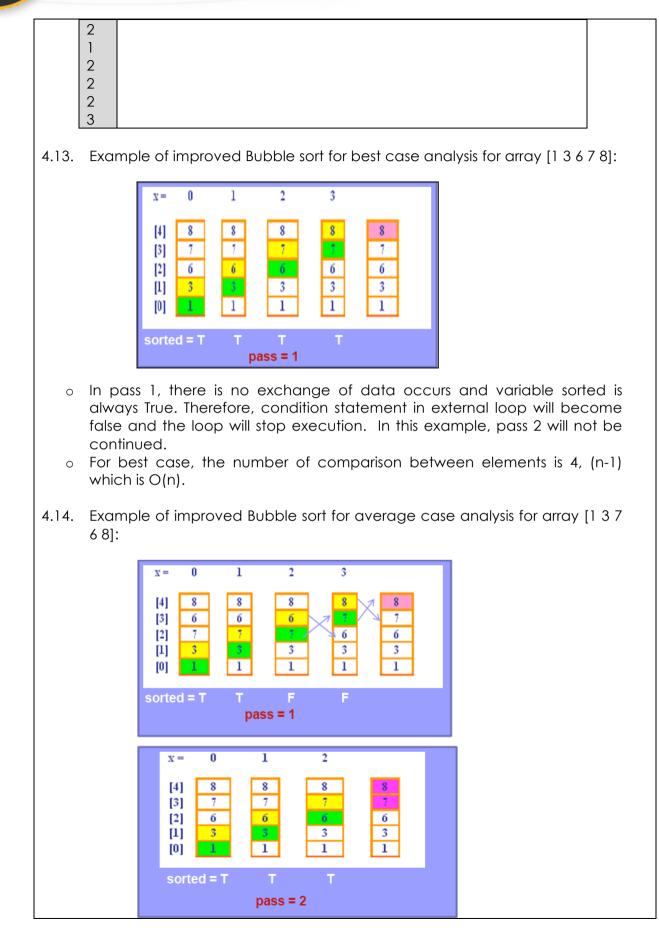


worst case and best case is the same - with 10 comparisons.

- The difference can be seen in the number of swapping elements. Worst case has maximum number of swapping: 10, while best case has no swapping since all data is already in the right position.
- For the best case, we can observe that starting with pass one, there is no exchange of data occur.
- From the example, it can be concluded that in any pass, if there is no exchange of data occur, the list is already sorted. The next pass shouldn't be continued and the sorting process should stop.
- 4.12. Improvement of the Bubble Sort algorithm
  - i. To improve the efficiency of Bubble Sort, a condition that check whether the list is sorted should be add at the external loop
  - ii. A Boolean variable, **sorted** is added in the algorithm to signal whether there is any exchange of elements occur in certain pass.
  - iii. In external loop, sorted is set to true. If there is exchange of data inside the inner loop, sorted is set to false.
  - iv. Another pass will continue, if sorted is false and will stop if sorted is true.











- For average case [1 3 7 6 8] we have to go through 2 passes only. The subsequent passes are not continued since the array is already sorted.
- Conclusion for improved Bubble Sort, the sorting time and the number of comparisons between data in average case and best case can be minimized.
- 4.15. Summary of bubble sort algorithm complexity (time consuming operations compares, swaps)
  - i. # of Compares
    - o a for loop embedded inside a while loop
    - Worst Case (n-1)+(n-2)+(n-3) ...+1 , or O(n2)
    - Best Case (n-1) or O(n)
  - ii. # of Swaps
    - inside a conditional -> #swaps data dependent !!
    - Best Case 0, or O(1)
    - Worst Case (n-1)+(n-2)+(n-3) ...+1 , or O(n2)
  - iii. Space
    - o size of the array
    - o an *in-place* algorithm

#### **5.0 SELECTION SORT**

- 5.1. Selection sort performs sorting by repeatedly find the next largest (or smallest) element in the array and put the element in the unprocessed portion of the array to the end of the unprocessed portion until the whole array is sorted.
- 5.2. To sort an array of record with selection sort, it works by taking multiple passes over the array with the following main activities
  - i. **Choose** the largest/smallest item in the array and place the item in its correct place.
  - ii. Choose the next larges/next smallest item in the array and place the item in its correct place.
  - iii. **Repeat** the process until all items are sorted.
- 5.3. Does not depend on the initial arrangement of the data and only appropriate for small  $n O(n^2)$  algorithm.

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	[0]	[1]	[2]	[3]	[4]	[5]	
1	12	8	3	21	99	1	Start - Unsorted List
	12	8	3	21	99	1	Base 1 Find the largest element in
	12	8	3	the array (99) and put at the last			
	12	8	3	21	1	99	<b>Pass 2</b> - Find the second largest element in the array (21) and put at
	12	8	3	1	21	99	the second last index of the array
	12	8	3	1	21	99	<b>Pass 3</b> - Find the next largest element in the array (12) and put at
	1	8	3	12	21	99	the current last index of the array
	1	8	3	12	21	99	Pass 4-Find the next largest
	1	3	8	12	21	99	element in the array (8) and put at the current last index of the array
	1	3	8	12	21	99	Pass 5-Find the next largest
	1	3	8	12	21	99	element in the array (3) and put at the current last index of the array
	swa		ogran	n 5.3 a		•	lementation are; <b>selectionSort()</b> and and 5.4 are the implementation of the two
•	swa	<b>p()</b> . Pr	ogran	n 5.3 a		•	5.4 are the implementation of the two last : index of the last item in the subarray of
	<b>swa</b> funct 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15	<pre>p(). Pro tions i  //Pro void :     {     for (         {// s         int         // l         for         {        i         // l         for         {            i         // l         for         {</pre>	gram select larges (int las arges (int p: f (Date large end for wap la bata[la ap(Da end for	5.3 5.3 ionSori t = n-1 largest stIndex t item i =1;p <= a[p] > stInde: r argest argest ast] ta[larg or	t(Datc ; last > t item c = 0; is assu = last; Data[ x <del>= p;</del> item l gestine	ogram	5.4 are the implementation of the two last : index of the last item in the subarray of items yet to be sorted. Data[], int n) -last)
	<b>swa</b> funct 1 2 3 4 5 6 7 8 9 10 11 12 13 14	<pre>p(). Pro tions i  //Pro void :     {     for (         {// s         int         // l         for         {        i         // l         for         {            i         // l         for         {</pre>	gram select larges (int las arges (int p: f (Date large end for wap la bata[la ap(Da end for	5.3 5.3 ionSor t = n-1 larges stIndex t item =1;p <= a[p] > stInde: r argest argest argest argest argest	t(Datc ; last > t item c = 0; is assu = last; Data[ x <del>= p;</del> item l gestine	ogram	5.4 are the implementation of the two last : index of the last item in the subarray of items yet to be sorted. Data[], int n) -last) Array start at index 0 tindex]) largestIndex] with largestIndex item found





 1
 //Program 5.4

 2
 void swap(DataType& x, DataType& y)

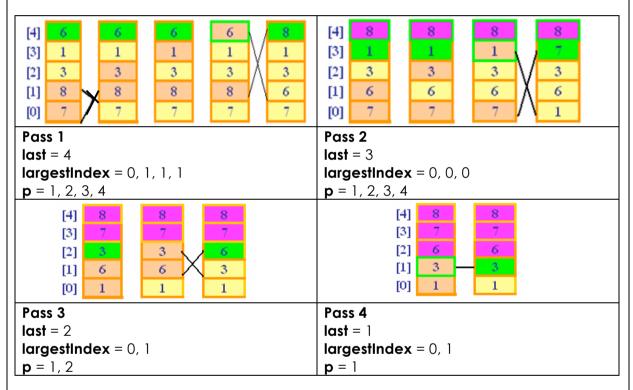
 3
 { DataType temp = x;

 4
 x = y;

 5
 y = temp;

 6
 } // end swap

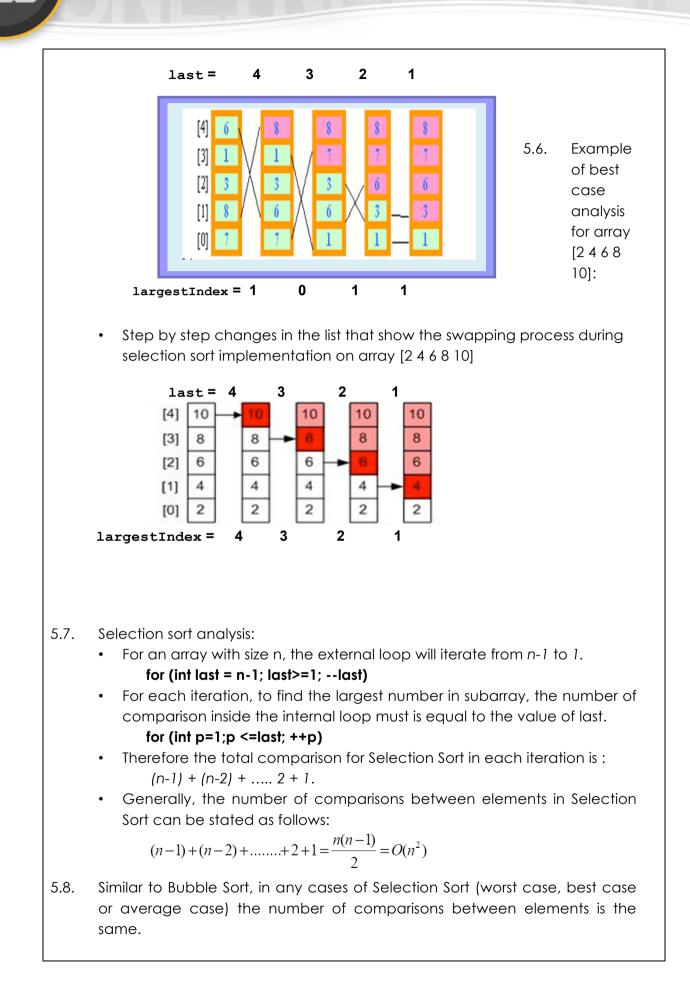
5.5. Example of selection sort implementation to sort array of integer [7 8 3 1 6] into ascending order:



- In pass 1, the largest value in the array will be searched from index 1 to index 4. The largest value is 8 and was found at index 1 and will be put at last(4). There are four comparisons in this pass.
- Below shows step by step changes in the list that show the swapping process during selection sort implementation on array [7 8 3 1 6].

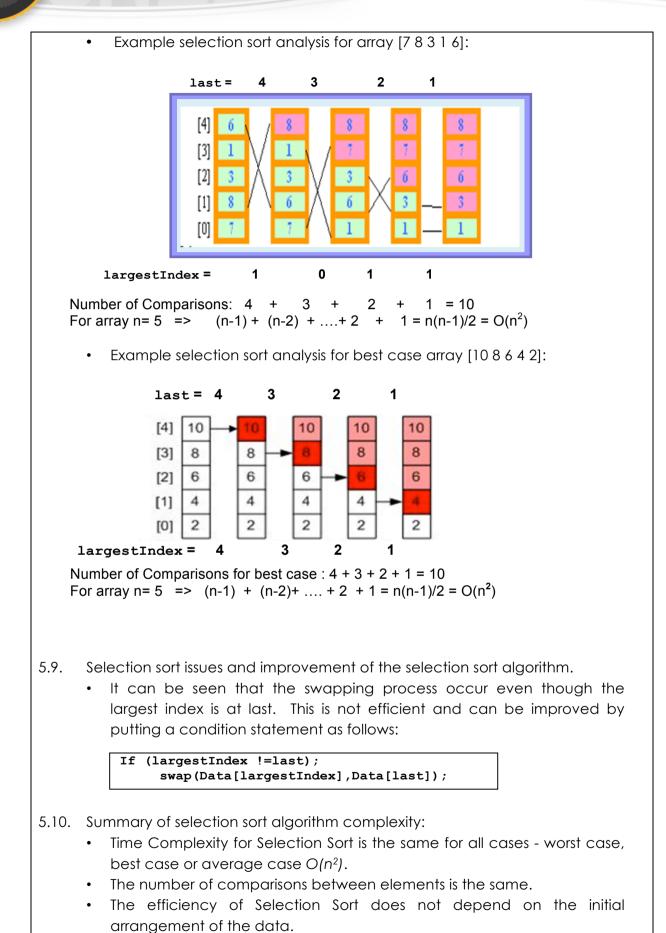
















#### **6.0 INSERTION SORT**

- 6.1. Insertion sort performs sorting by repeatedly removes an element from the unsorted region, inserting it into the correct position in sorted region list, until all regions become sorted.
- 6.2. To sort an array of record with selection sort, it works by taking multiple passes over the array with the following main activities
  - Partition the array into two regions: sorted and unsorted
    - i. Take each item from the unsorted region and insert it into its correct order in the sorted region

ii. Find next unsorted element and Insert it in correct place, relative to the ones already sorted

- 6.3. Insertion Sort is appropriate for small arrays due to its simplicity.
- 6.4. Example of Insertion sort operation with list of 6 elements [21 8 3 12 99 1] is as follows:

[0]	[1]	[2]	[3]	[4]	[5]	
21	8	3	12	99	1	Start - Unsorted List
21	8	3	12	99	1	Insert 8 before 21: Created the sorted region from index [0] to [1], the unsorted region from
8	21	3	12	99	1	index [2] to [5]
8	21	3	12	99	1	Insert 3 before 8: Created the sorted region from index
3	8	21	12	99	1	[0] to [2], the unsorted region from index [3] to [5]
3	8	21	12	99	1	Insert 12 before 21:
3	8	12	21	99	1	Created the sorted region from index [0] to [3], the unsorted region from
3	8	12	21	99	1	Keep 99 in place:
3	8	12	21	99	1	Created the sorted region from index [0] to [4], the unsorted region from
3	8	12	21	99	1	index [5] Insert 1 before 3:
1	3	8	12	21	99	All elements are in sorted region



6.5.

2

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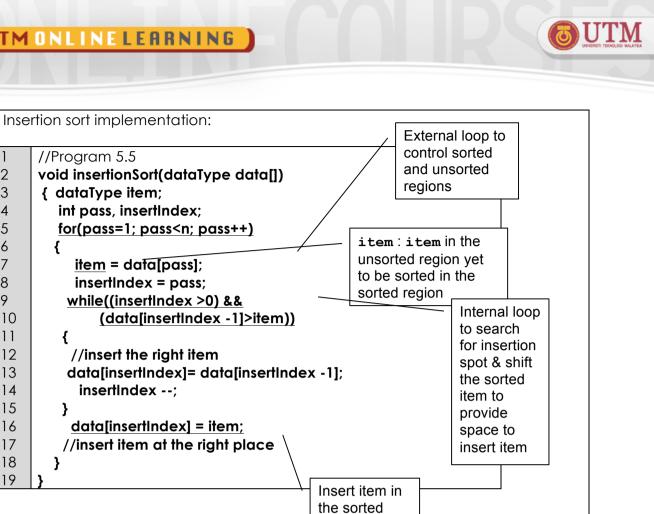
19

{

{

}

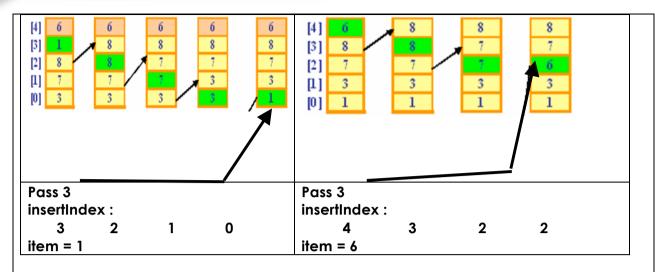
}



6.6. Example of insertion sort implementation to sort array of integer [7 8 3 1 6] into ascending order:

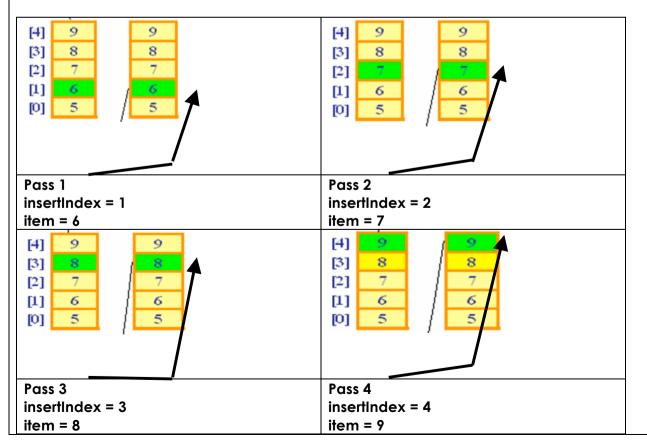
region

[4] 6 [3] 1 [2] 3 [1] 8 [0] 7 7	[4]       6       6       6       6         [3]       1       1       1         [2]       3       8       8       8         [1]       8       8       7       7         [0]       7       7       5       3
Pass 1	Pass 2
insertIndex :	insertIndex :
1	2 1 0
item = 8	item = 3

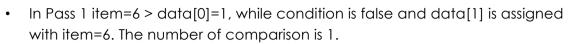


- In Pass 1, item=8 > data[0]=7. while loop condition is false, therefore data[1] will be assigned with item = 8. The number of comparison is 1.
- In Pass 2, item to be insert is 3. Insertion point is from indeks 0-2, which is between 7 and 8. The number of comparison is 2.
- In Pass 3, item to be insert is 1. Insertion point is from indeks 0-3, which is between 3, 7 and 8. The number of comparison is 3.
- In Pass 4, item to be insert is 6. Insertion point is from indeks 0-4, which is between 1,3, 7 and 8. at index, item (6) > data[1]=3, while loop condition is false and therefore data[2] is assigned with value for item = 6. The number of comparison is 4.

#### 6.7. Example of a best case analysis for array [5 6 7 8 9]:







- In Pass 2 item=7 > data[1]=1, while condition is false and data[2] is assigned with item=7. The number of comparison is 1.
- In Pass 3 item=8 > data[1]=1, while condition is false and data[3] is assigned with item=8. The number of comparison is 1.
- In Pass 3 item=9 > data[1]=1, while condition is false and data[4] is assigned with item=9. The number of comparison is 1.
- There are 4 passes to sort array with elements [5 6 7 8 9]. In each pass there is only 1 comparison.

Example:

Pass 1, 1 comparison Pass 2, 1 comparison Pass 3, 1 comparison Pass 4, 1 comparison

- In this example, the total comparisons for an array with size 5 are 4. Therefore, for best case, the number of comparison is n-1 which gives linear time complexity linear O(n).
- 6.8. The worst case for insertion sort is when we have totally unsorted data. In each pass, the number of iteration for while loop is maximum.
- 6.9. For example worst case with 4 elements array.

Pass 4, 4 comparison - (n-1)

Pass 3, 3 comparison -(n-2)

Pass 2, 2 comparison -(n-3)

Pass 1, 1 comparison - (n-4)

• The number of comparisons between elements in Insertion Sort can be stated as follows:

$$\sum_{i=1}^{n-1} i = (n-1) + (n-2) + \dots + 2 + 1 = \frac{n(n-1)}{2} = O(n^2)$$

- Example of worst case analysis for array [9 7 5 3 1]:
  - Pass 4 Have to compare data at data[4-1], data[4-2], data[4-3] and data[4-4].

Pass 3 - Have to compare data at data[3-1], data[3-2] and data[3-3].

- Pass 2 Have to compare data at data[2-1], and data[2-2].
- Pass 1 Have to compare data at data[1-1] only
- The number of comparison is 10. i.e. (5-1)+(5-2)+(5-3)+(5-4) = 10.



#### 6.10. Summary of insertion sort algorithm complexity:

- How many **compares** are done?
  - 1+2+...+(n-1), O(n<sup>2</sup>) for worst case
  - (n-1)\* 1 , O(n) for best case
- How many element **shifts** are done?
  - 1+2+...+(n-1), O(n<sup>2</sup>) for worst case
  - 0, O(1) for best case
- How much space?
  - In-place algorithm

#### 7.0 SUMMARY OF QUADRATIC SORTING ALGORITHMS COMPLEXITY

Efficiency	Insertion	Bubble	Selection	
Comparisons:				
Best Case	O (n)	O(n²)	O(n <sup>2</sup> )	
Average Case	O(n <sup>2</sup> )	O(n <sup>2</sup> )	O(n <sup>2</sup> )	
Worst Case	O(n <sup>2</sup> )	O(n <sup>2</sup> )	O(n <sup>2</sup> )	
Swaps				
Best Case	0	0	O(n)	
Average Case	O(n <sup>2</sup> )	O(n <sup>2</sup> )	O(n)	
Worst Case	O(n <sup>2</sup> )	O(n <sup>2</sup> )	O(n)	

#### 8.0 MERGE SORT

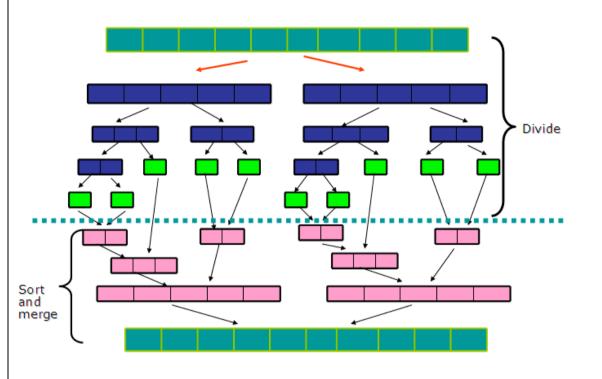
8.1. Merge Sort applies **divide** and **conquer** strategy. First, the list to be sorted is separated into two groups (*Divide*), *recursively* each group is sorted independently (*Conquer*) and then the two sorted groups are merged to a sorted sequence (*Combine*).

#### 8.2. Three main steps in Merge Sort algorithm:

- i. Divide an array into halves
- ii. Sort each half
- iii. Merge the sorted halves into one sorted array
- 8.3. The performance is independent of the initial order of the array items.



8.4. Illustration of the recursive Merge Sort algorithm strategy.



- 8.5. Two functions in merge sort implementation are;
  - MergeSort() and Merge().

#### i. mergeSort()function

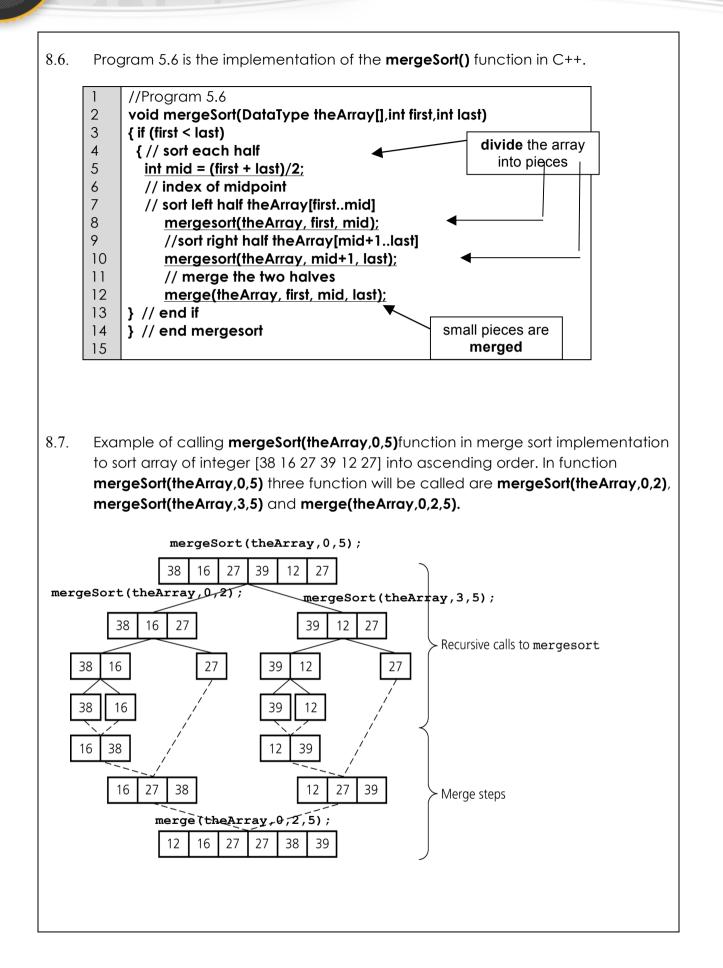
- A recursive function that divide the array into pieces until each piece contain only one item.
- The small pieces are merge into larger sorted pieces until one sorted array is achieved.

#### ii. merge()function

- Compares an item into one half of the array with item in the other half of the array and,
- $\circ$   $\,$  Moves the smaller item into temporary array.
- Then, the remaining items are simply moved to the temporary array.
- The temporary array is copied back into the original array.





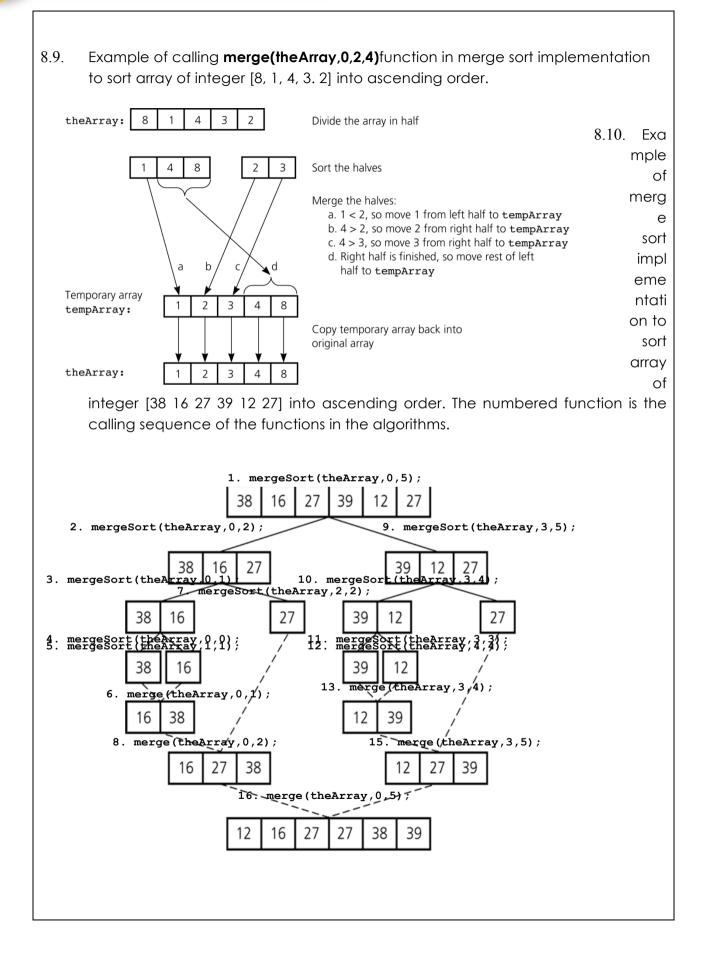






8.8.	Program 5.7 is the implementation of the <b>merge()</b> fund	ction in C++.
1 2 3 4 5 6 7 8 9 10	<pre>//Program 5.7 const int MAX_SIZE = maxNmbrItemInArry; void merge(DataType theArray[],</pre>	Duplicate the positions
10 11 12 13 14 15 16 17 18 19 20 21 22 23	<pre>// while both subarrays are not empty, // copy the smaller item into the temporary array int index = first1; // next available location in tempArray for (; (first1 &lt;= last1) &amp;&amp; (first2 &lt;= last2); ++index) {if (theArray[first1] &lt; theArray[first2]) { tempArray[index] = theArray[first1]; ++first1; } else { tempArray[index] = theArray[first2]; ++first2; } }// end if</pre>	Moves the smaller item into temporary array
24 25 26 27 28 29 30 31 32 33	for (; first1 <= last1; ++first1, ++index) tempArray[index] = theArray[first1]; // finish off the second subarray, if necessary for (; first2 <= last2; ++first2, ++index) tempArray[index] = theArray[first2]; // copy the result back into the original array	move the remaining items to the temporary array The temporary
34 35 36 37 38 39 40	for (index = first;index <= last; ++index) theArray[index] = tempArray[index]; } // end merge function	array is copied back into the original array









```
    The execution of the C++ program to sort array of integers :
[38 16 27 39 12 27]
into ascending order gives the following sequence of output tracing.
```

```
Unsorted data [38 16 27 39 12 27]
```

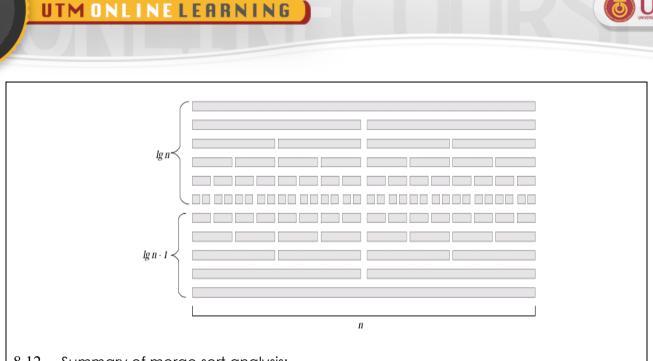
```
14. mergeSort(theArray,5,5);
Content of divided sublist with first=0 & last=5 [38 16 27 39 12 27]
Content of divided sublist with first=0 & last=2 [38 16 27]
Content of divided sublist with first=0 & last=1 [38 16]
Content of divided sublist with first=0 & last=0 [38]
Content of divided sublist with first=1 & last=1 [16]
Content of merged list with first=0 & last=1 [16 38]
Content of divided sublist with first=2 & last=2 [27]
Content of merged list with first=0 & last=2 [16 27 38]
Content of divided sublist with first=3 & last=5 [39 12 27]
Content of divided sublist with first=3 & last=4 [39 12]
Content of divided sublist with first=3 & last=3
                                                  [39]
Content of divided sublist with first=4 & last=4
                                                  [12]
Content of merged list with first=3 & last=4 [12 39]
Content of divided sublist with first=5 & last=5 [27]
Content of merged list with first=3 & last=5 [12 27 39]
Content of merged list with first=0 & last=5 [12 16 27 27 38 39]
Sorted data [12 16 27 27 38 39]
Press any key to continue . . .
```

#### 8.11. Merge sort analysis:

- The list is always divided into two balanced list (or almost balanced for odd size of list)
- The number of calls to repeatedly divide the list until there is one item left in the list is:

 $n + 2\frac{n}{2} + 4\frac{n}{4} + 8\frac{n}{8} + 16\frac{n}{16} + \dots x\frac{n}{x}$ 

- Assuming that the left segment and the right segment of the list have the equal size (or almost equal size), then  $x \approx \lg n$ . The number of iteration is approximately  $n \lg n$ .
- The same number of repetition is needed to sort and merge the list (refer to the following illustration). Thus, as a whole the number of steps needed to sort data using merge sort is 2*n lg n*, which is O(*n lg n*).



- 8.12. Summary of merge sort analysis:
  - Worse Case Analysis : O(n \* log2n)
  - Average case Analysis: O(n \* log2n)
  - Performance is independent of the initial order of the array items
  - Advantage Merge sort is an extremely fast algorithm
  - Disadvantage Merges sort requires a second array (temporary array) as large as the original array

#### 9.0 QUICK SORT

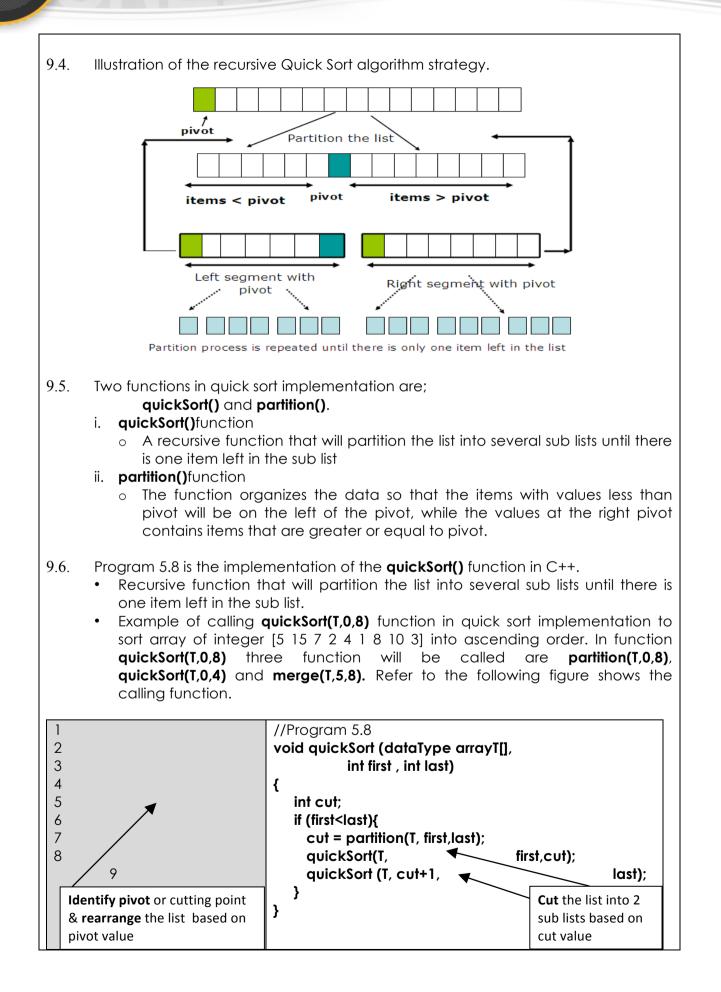
- 9.1. Quick sort is similar with Merge sort in using **divide** and **conquer** technique.
- 9.2. Differences of Quick sort and Merge sort :

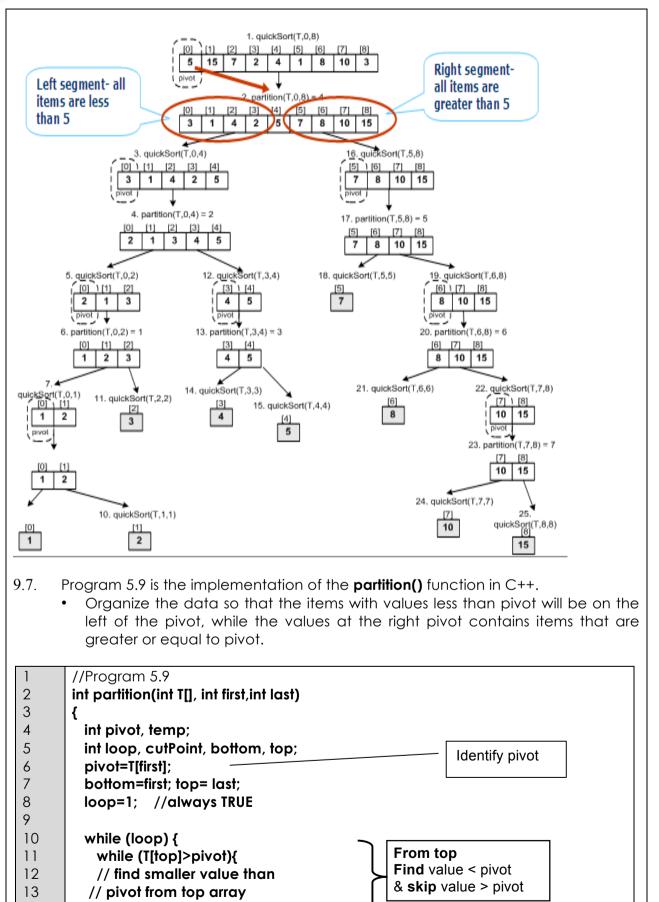
Quick Sort	Merge Sort
Partition the list based on the pivot	Partition the list by dividing the list
value	into two
No merge operation is needed since	Merge operation is needed to
when there is only one item left in the	sort and merge the item in the
list to be sorted, all other items are	left and right segment.
already in sorted position.	

- 9.3. The **divide-and-conquer** algorithm strategy:
  - i. **Choose** a pivot (first element in the array)
    - ii. Partition the array about the pivot
      - o items < pivot
      - items >= pivot
      - o Pivot is now in correct sorted position
  - iii. Sort the left section again until there is one item left
  - iv. Sort the right section again until there is one item left







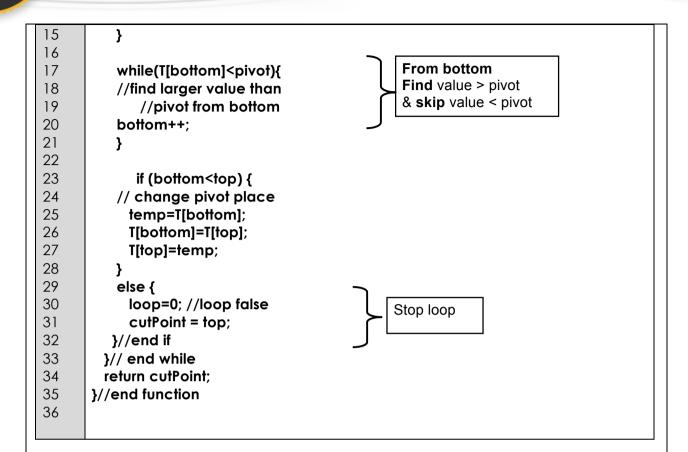


14

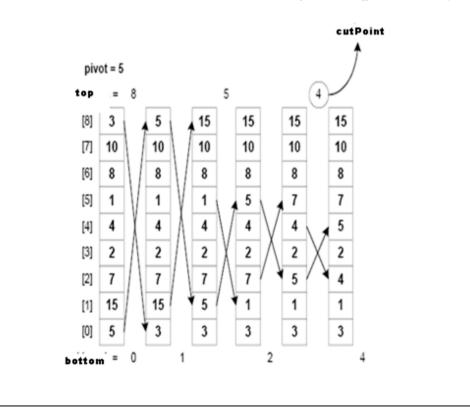
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• The following figure shows example of calling **partition(T,0,8)** function in quick sort implementation to sort array of integer [5 15 7 2 4 1 8 10 3] into ascending order. After execution of function **partition()**, pivot 5 will be placed at index 4 and the value 4, will be returned to function **quickSort()** for further partition.



9.8. Referring to the quick sort implementation figure at point 9.6, the number at the sequence of calling functions for **quickSort()** and **partition()** functions can be mapped with the following output display.

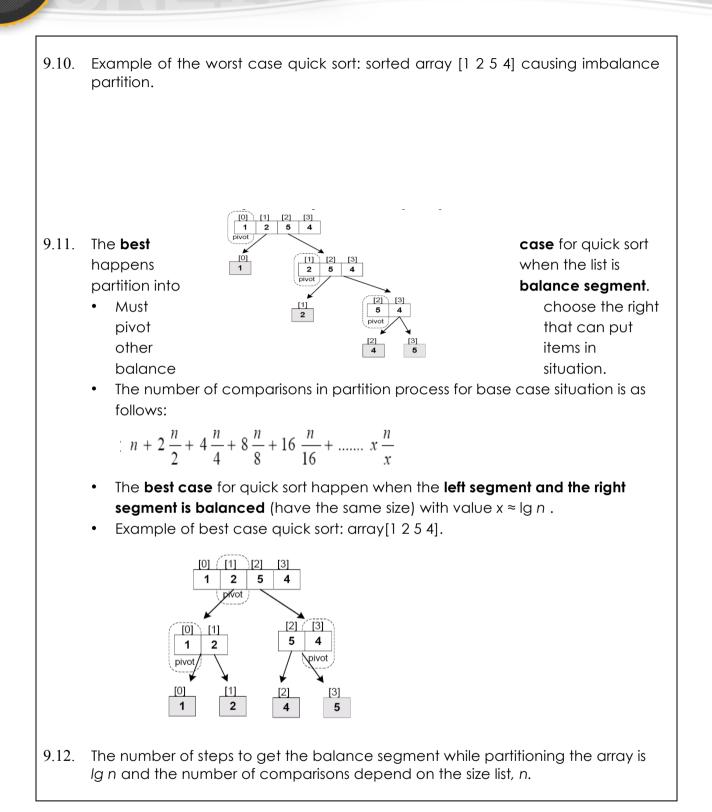
```
Content of the array before sorting : 5 15 7 2 4 1 8
The sublist \rightarrow 1 with pivot = 5
3 15 7 2 4 1 8 10 3
The sublist \rightarrow 2 with pivot = 3
314125
The sublist \rightarrow 3 with pivot = 2
2 1 3
The sublist \rightarrow 4 with pivot = 1
1 2
The sublist \rightarrow 5 with one piece item = 1
The sublist \rightarrow 6 with one piece item = 2
The sublist \rightarrow 7 with one piece item = 3
The sublist \rightarrow 8 with pivot = 4
4 5
The sublist \rightarrow 9 with one piece item = 4
The sublist \rightarrow 10 with one piece item = 5
The sublist -> 11 with pivot = 7
7 8 10 15
The sublist \rightarrow 12 with one piece item = 7
The sublist -> 13 with pivot = 8
8 10 15
The sublist \rightarrow 14 with one piece item = 8
The sublist \rightarrow 15 with pivot = 10
10 15
The sublist \rightarrow 16 with one piece item = 10
8 10 15
The sublist \rightarrow 17 with one piece item = 15
8 10 15
```

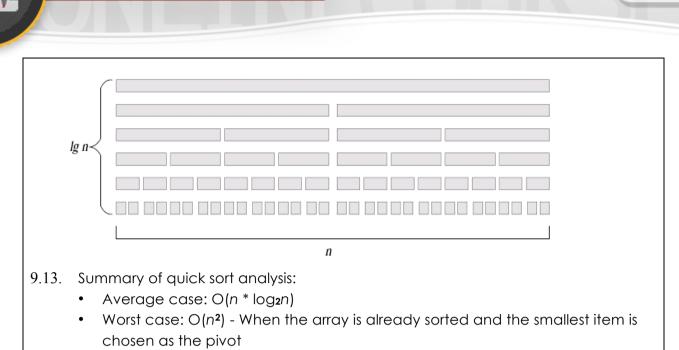
9.9. Quick sort analysis.

- The efficiency of quick sort depends on the **pivot value**.
- This class chose the first element in the array as pivot value.
- However, pivot can also be chosen at **random**, or **from the last element** in the array.
- The **worst case** for quick sort occurs when the **smallest** item or the **largest** item always be chosen as **pivot** value causing the left partition and the right partition not balance.









• Quicksort is usually extremely fast in practice

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• Even if the worst case occurs, quicksort's performance is acceptable for moderately large arrays

#### **10.0 SUMMARY**

- 10.1. Order-of-magnitude analysis and Big O notation measure an algorithm's time requirement as a function of the problem size by using a growth-rate function.
- 10.2. To compare the efficiency of algorithms
  - i. Examine growth-rate functions when problems are large
  - ii. Consider only significant differences in growth-rate functions
- 10.3. Worst-case and average-case analyses
  - Worst-case analysis considers the maximum amount of work an algorithm will require on a problem of a given size
  - Average-case analysis considers the expected amount of work that an algorithm will require on a problem of a given size
- 10.4. Order-of-magnitude analysis can be the basis of your choice of an ADT implementation.
- 10.5. Selection sort, Bubble sort, and Insertion sort are all  $O(n^2)$  algorithms. Quick sort and merge sort are two very fast recursive sorting algorithms.





10.6. Approximate growth rates of time required for eight sorting algorithms.

	Worst case	Average case
Selection sort	n <sup>2</sup>	n <sup>2</sup>
Bubble sort	n <sup>2</sup>	n <sup>2</sup>
Insertion sort	n <sup>2</sup>	n <sup>2</sup>
Mergesort	n * log n	n * log n
Quicksort	n <sup>2</sup>	n * log n

10.7. A comparison of growth-rate functions shows that  $O(n \log n)$  algorithm is significantly faster than  $O(n^2)$  algorithm.

				n		
Function	10	100	1,000	10,000	100,000	1,000,000
1	1	1	1	1	1	1
log <sub>2</sub> n	3	6	9	13	16	19
n	10	10 <sup>2</sup>	10 <sup>3</sup>	104	105	106
n ∗log₂n	30	664	9,965	10 <sup>5</sup>	10 <sup>6</sup>	10 <sup>7</sup>
n²	10 <sup>2</sup>	104	106	10 <sup>8</sup>	10 <sup>10</sup>	10 <sup>12</sup>
n³	10 <sup>3</sup>	10 <sup>6</sup>	10 <sup>9</sup>	10 <sup>12</sup>	10 <sup>15</sup>	10 18
2 <sup>n</sup>	10 <sup>3</sup>	1030	1030	<sup>1</sup> 10 <sup>3,01</sup>	<sup>0</sup> 10 <sup>30,1</sup>	103 10 301,030