

SSCM 1313

C++ COMPUTER PROGRAMMING

Chapter 6: Class, Object and Function

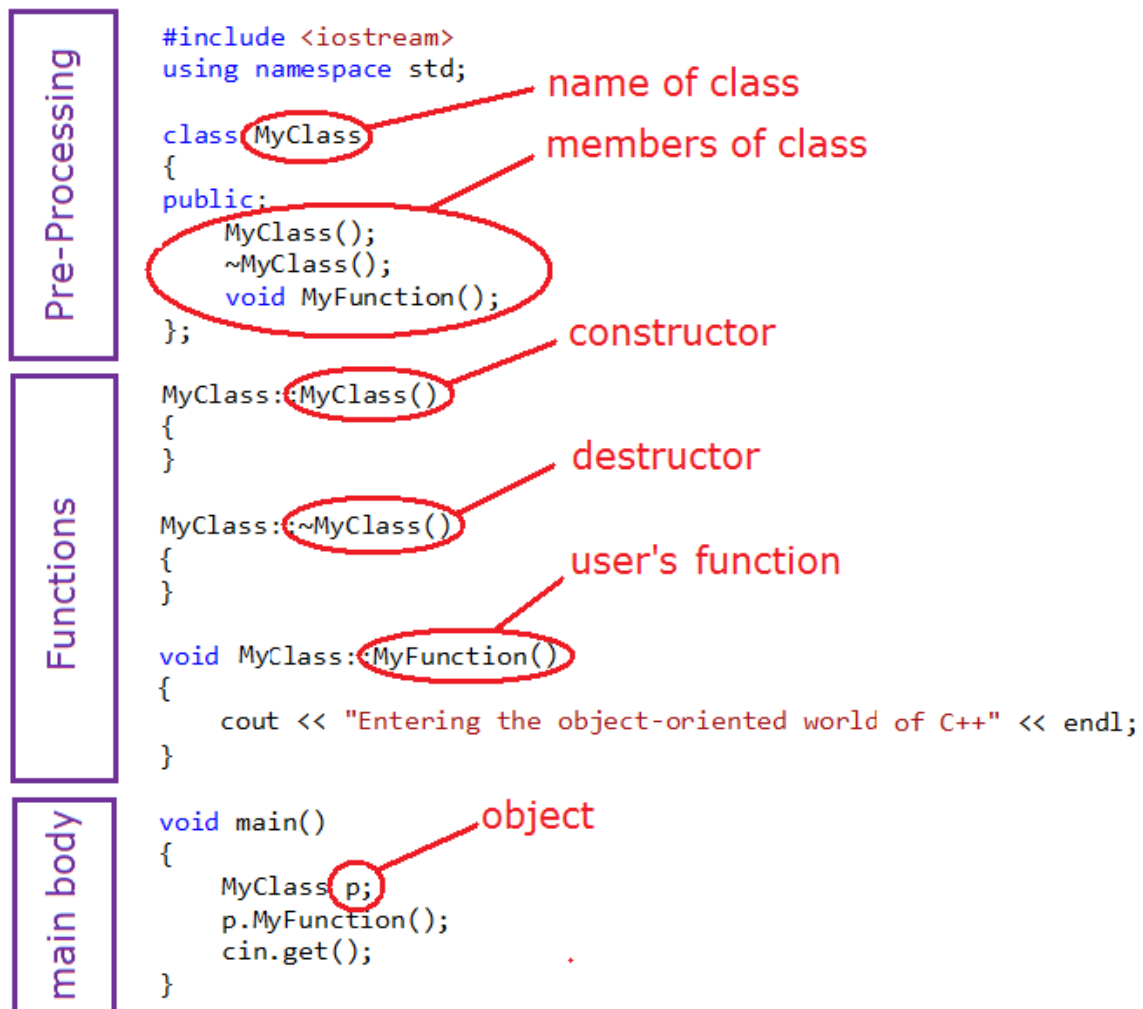
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Class, Object and Function

Object-oriented approach:

Function. Classes and their objects, Constructor/ destructor and function overloading. Inheritance, class collaboration and polymorphism. Dynamic memory allocation. Applications in graph theoretical and matrix problems.

C++ Language Organization



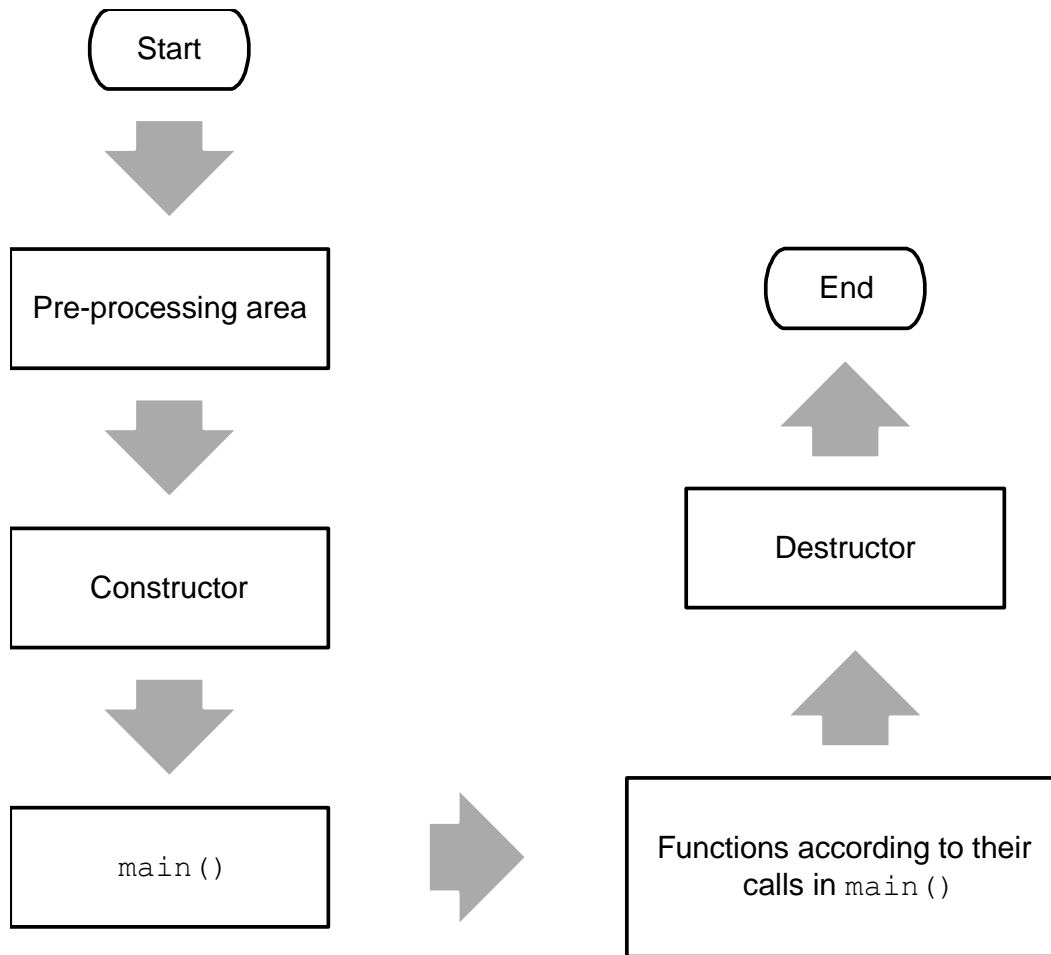


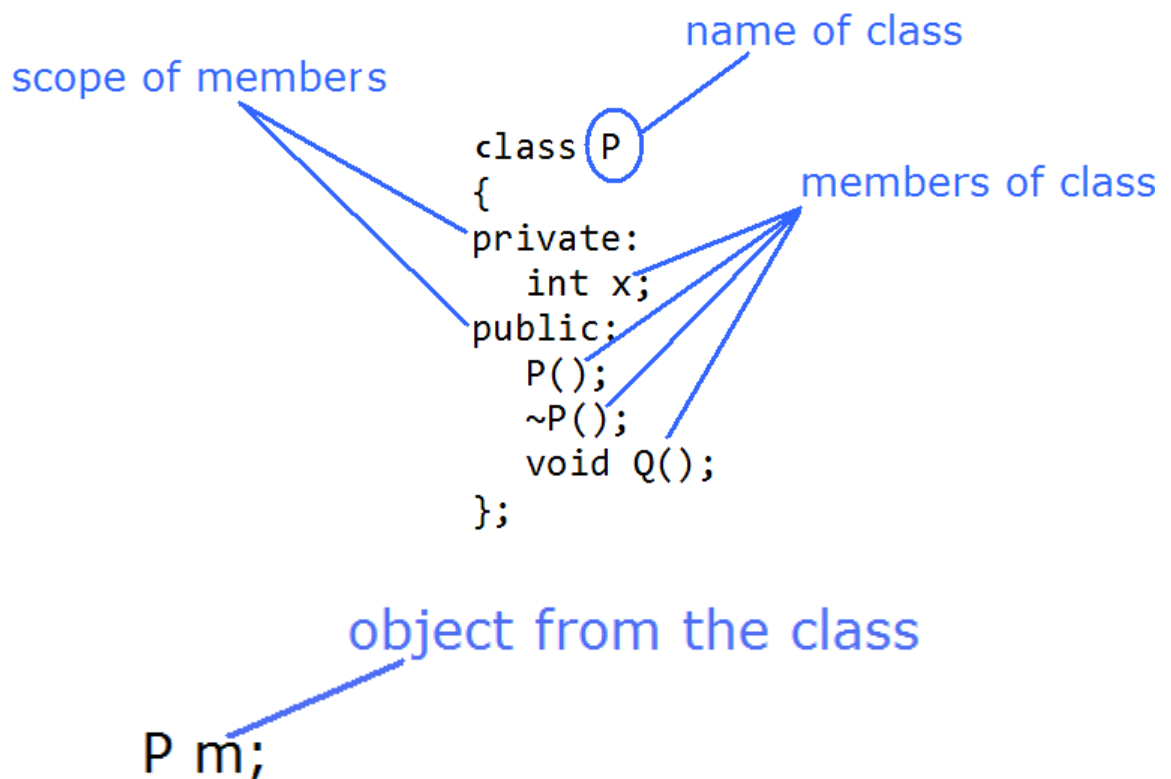
Figure 6.1. Order of execution in a typical C++ program.

Class

- a grouping of variables and functions that have a common ancestor
- a special form of structure
- *object* is an instance of a class
- members of a class consist of variables, functions and structures, which are global

```
class Name of Class
{
private:
    List of variables
public:
    List of variables and functions
};
```

Example:



Visibility of Members

- Members of a class are variables, structures and functions
- Each member are global, and its scope is either private or public

private

- for variables or structures only
- the scope is global but limited to member functions only

public

- for variables, structures and functions
- The scope covers the whole program including non-member functions

Function

- a module or one unit of work in a program that can be called for solving a given problem
- Needed in order to make the program structured and modular
- A function must have a name.
- A function must belong and declared into a class.
- A function must be a prototype from one of the followings

```
void
int
float
double
char
bool
```

- A function of type other than `void` must return a value, and its return value is received by a variable from another function.
- A function may include argument(s) for passing or receiving data to another function.

```
type ClassName :: FunctionName(arguments)
{
    // body of statements
}
```

Example:

```
double f(int x, double y)
{
    double z;
    y=(int)2*x-1;
    z=3*cos(y);
    return z;
}
```

Special Functions

Constructor

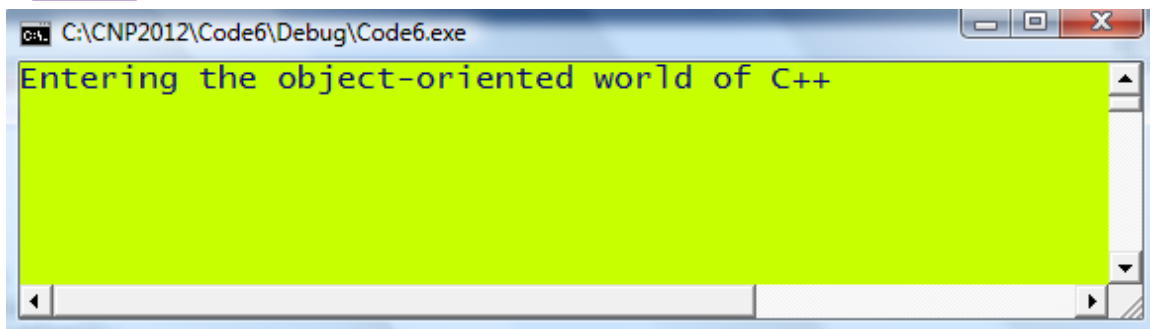
- A special function which has the same name as the class
- a function with no specific class
- allocates memory for the class
- a suitable place for initializing global variables

Destructor

- a special function which has the same name as the class preceded with a tilde
- a function with no specific class
- deallocates memory from the class
- a suitable place for destroying global variables and arrays

VC2010 **Code6A.cpp**: Class and object.

Pre-Processing	<pre>#include <iostream> using namespace std; class MyClass { public: MyClass(); ~MyClass(); void MyFunction(); };</pre>	<p>name of class</p> <p>members of class</p> <p>constructor</p>
Functions	<pre>MyClass::MyClass() { } MyClass::~MyClass() { } void MyClass::MyFunction() { cout << "Entering the object-oriented world of C++" << endl; }</pre>	<p>destructor</p> <p>user's function</p>
main body	<pre>void main() { MyClass p; p.MyFunction(); cin.get(); }</pre>	<p>object</p>



C:\CNP2012\Code6\Debug\Code6.exe

```
Entering the object-oriented world of C++
```


VC2010 Code6B.cpp: Class, object and method.

```

#include <iostream>
using namespace std;
class MyClass
{
public:
    int x,y;
    MyClass();
    ~MyClass();
    void MyFunction();
};

MyClass::MyClass() // constructor
{
    x=5; y=-7;
}

MyClass::~~MyClass() // destructor
{
}

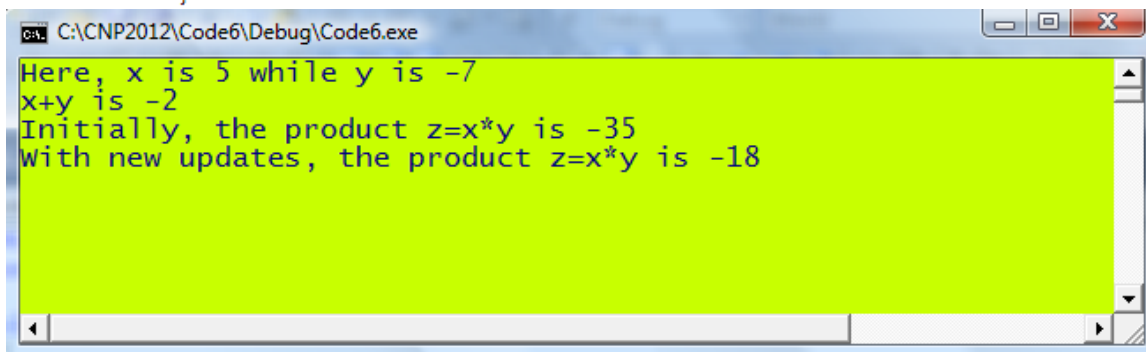
void MyClass::MyFunction()
{
    cout << "Here, x is " << x << " while y is " << y << endl;
    cout << "x+y is " << x+y << endl;
}

void main()
{
    int z;
    MyClass p;
    p.MyFunction();
    z=p.x*p.y;
    p.x=2; p.y=-9;
    z=p.x*p.y;
    cout << "With new updates, the product z=x*y is " << z << endl;
    cin.get();
}

```

visible everywhere

z is a local variable,
p.x and p.y are global



VC2010 Code6C.cpp: Class construction.

```

#include <iostream>
#define PI 3.142
using namespace std;

class Sphere
{
private:
    double r, V, A, x, y, z;
public:
    Sphere (double, double, double);
    ~Sphere ();
    double Radius (), Volume (), SurfaceArea ();
};

Sphere::Sphere (double u, double v, double w)
{
    x=u; y=v; z=w;
}

Sphere::~Sphere ()
{
    cout << "Sphere class destroyed" << endl;
}

double Sphere::Radius ()
{
    r=sqrt (x*x+y*y+z*z);
    return r;
}

double Sphere::Volume ()
{
    V=4*PI*r*r*r/3;
    return V;
}

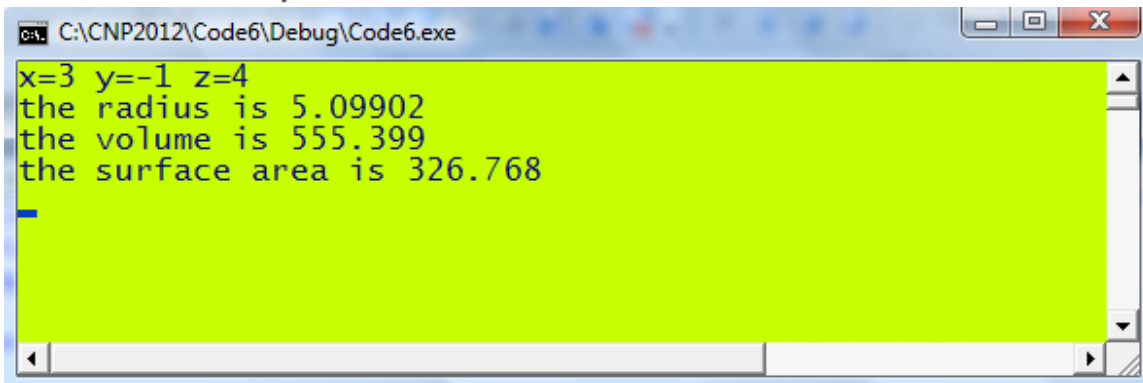
double Sphere::SurfaceArea ()
{
    A=4*PI*r*r;
    return A;
}

void main ()
{
    Sphere s (3, -1, 4);
    cout << "the radius is " << s.Radius () << endl;
    cout << "the volume is " << s.Volume () << endl;
    cout << "the surface area is " << s.SurfaceArea () << endl;
    cin.get ();
}
  
```

visible everywhere except in main()

u, v and w are local variables

function returns a double value



VC2010 **Code6D.cpp**: Class construction in a compact form.

```

#include <iostream>
#define PI 3.142
using namespace std;

class Sphere
{
public:
    Sphere(double u, double v, double w) {x=u; y=v; z=w;}
    ~Sphere() {}
    double r, x, y, z;
    double Radius() {return (r=sqrt(x*x+y*y+z*z));}
    double Volume() {return (4*PI*r*r*r/3);}
    double SurfaceArea() {return (4*PI*r*r);}
};

void main()
{
    Sphere s(3, -1, 4);
    cout << "x=" << s.x << " y=" << s.y << " z=" << s.z << endl;
    cout << "the radius is " << s.Radius() << endl;
    cout << "the volume is " << s.Volume() << endl;
    cout << "the surface area is " << s.SurfaceArea() << endl;
    cin.get();
}
    
```

visible everywhere inside the program

Function Overloading

- Different functions using the same name

VC2010 **Code6E.cpp**: Constructor overloading.

```
#include <iostream.h>
#include <math.h>
#define PI 3.142

class Sphere
{
public:
    Sphere();
    Sphere(double, double, double);
    ~Sphere() { }
    double r, x, y, z;
    double Radius(), Volume(), SurfaceArea();
};

Sphere::Sphere()
{ }

Sphere::Sphere(double u, double v, double w)
{
    x=u; y=v; z=w;
}

double Sphere::Radius()
{
    r=sqrt(x*x+y*y+z*z);
    return r;
}

double Sphere::Volume()
{
    return (4*PI*r*r*r/3);
}

double Sphere::SurfaceArea()
{
    return (4*PI*r*r);
}

void main()
{
    Sphere s(3, -1, 4);
    cout << "x=" << s.x << " y=" << s.y << " z=" << s.z << endl;

    cout << "the radius is " << s.Radius() << endl;
    cout << "the volume is " << s.Volume() << endl;
    cout << "the surface area is " << s.SurfaceArea() << endl;
};
```

function overloading

2 different functions
using the same name,
but differ in their
arguments

VC2010 Code6F.cpp: Overloading in functions.

```

#include <iostream.h>

class MyGraph
{
public:
    MyGraph()                {}
    ~MyGraph()               {}
    void MyFunction(int);
    void MyFunction(int,double);
    void MyFunction(int, char *);
    void MyFunction(int, double, char *);
};

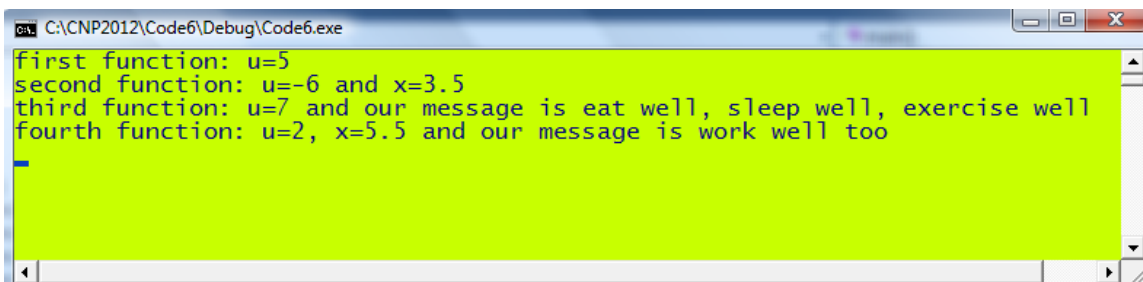
void MyGraph::MyFunction(int u)
{
    cout << "first function: u=" << u << endl;
}

void MyGraph::MyFunction(int u, double x)
{
    cout << "second function: u=" << u << " and x=" << x << endl;
}

void MyGraph::MyFunction(int u, char *s)
{
    cout << "third function: u=" << u << " and our message is " << s << endl;
}

void MyGraph::MyFunction(int u, double x, char *s)
{
    cout << "fourth function: u=" << u << "
        << ", x=" << x << " and our message is " << s << endl;
}

void main()
{
    MyGraph g;
    g.MyFunction(5);
    g.MyFunction(-6, 3.5);
    g.MyFunction(7, "eat well, sleep well, exercise well");
    g.MyFunction(2, 5.5, "work well too");
}
  
```



```

C:\CNP2012\Code6\Debug\Code6.exe
first function: u=5
second function: u=-6 and x=3.5
third function: u=7 and our message is eat well, sleep well, exercise well
fourth function: u=2, x=5.5 and our message is work well too
  
```

Data Passing

- The transfer of data from one function to another

Rules for data passing between functions

- both the passing and receiving functions must be declared with the same prototypes
- both the passing and receiving functions must match in their argument types and prototypes

VC2010 **Code6G.cpp**: Data passing between functions.

```

#include <iostream.h>
#include <math.h>
#define PI 3.142

class Sphere
{
public:
    Sphere()    { }
    ~Sphere()   { }
    double Radius();
    double Volume(double);
    double SurfaceArea(double);
};

double Sphere::Radius()
{
    double x,x=3,y=-1,z=4;
    r=sqrt(x*x+y*y+z*z);
    return r;
}

double Sphere::Volume(double r)
{
    double V;
    V=4*PI*r*r*r/3;
    return V;
}

double Sphere::SurfaceArea(double r)
{
    double A;
    A=4*PI*r*r;
    return A;
}

void main()
{
    Sphere s;
    double R;
    R=s.Radius();
    cout << "the radius is " << R << endl;
    cout << "the volume is " << s.Volume(R) << endl;
    cout << "the surface area is " << s.SurfaceArea(R) << endl;
}

```

VC2010 Code6H.cpp: Array passing between functions.

```

#include <iostream.h>
#include <math.h>
#define PI 3.142
#define N 3

class Sphere
{
public:
  Sphere() {}
  ~Sphere() {}
  void Radius(double *r), Volume(double *v), SurfaceArea(double *a);
};

void Sphere::Radius(double *r)
{
  double *x,*y,*z;
  x=new double [N+1]; y=new double [N+1]; z=new double [N+1];
  for (int i=1;i<=N;i++)
  {
    x[i]=i; y[i]=i*i/5; z[i]=(i-5)/7;
    r[i]=sqrt(x[i]*x[i]+y[i]*y[i]+z[i]*z[i]);
  }
  delete x,y,z;
}

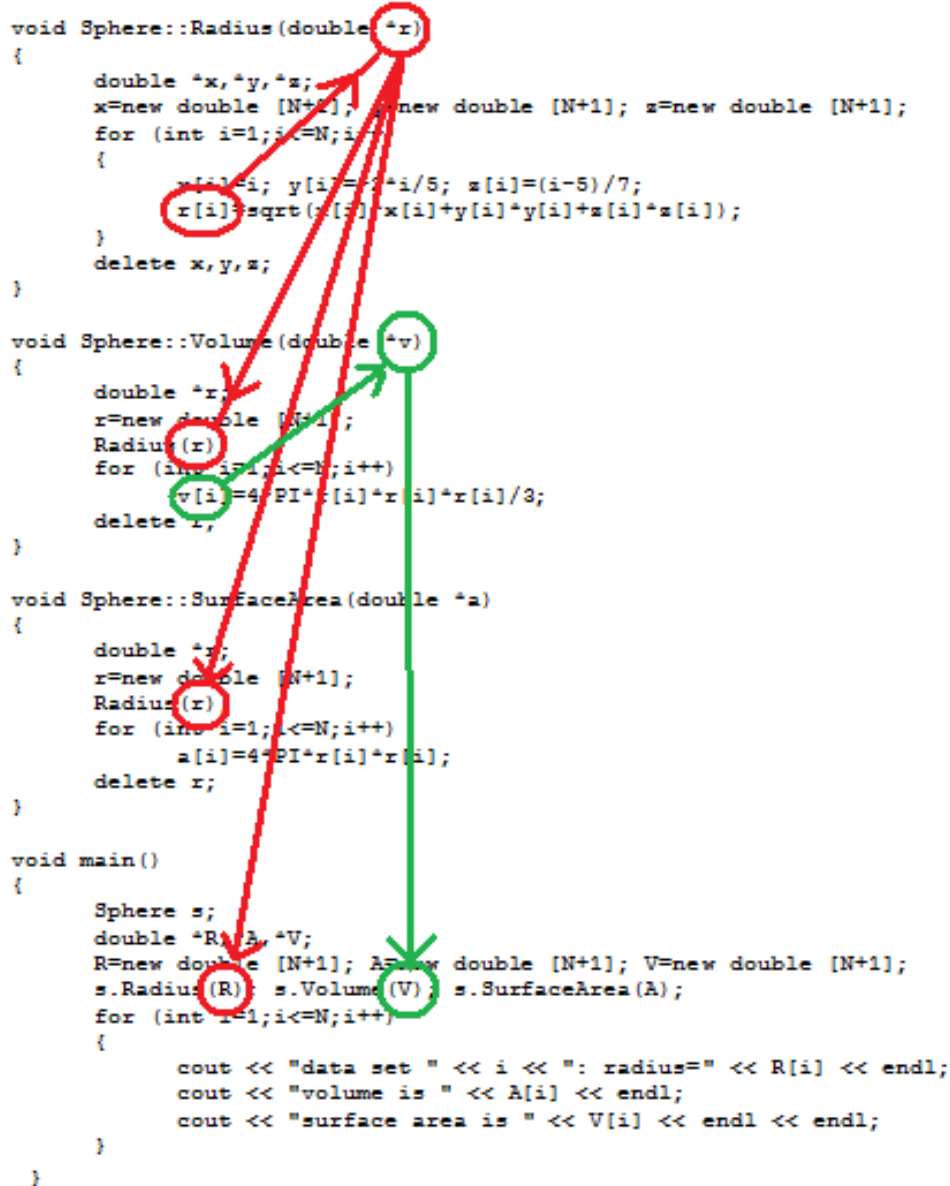
void Sphere::Volume(double *v)
{
  double *r;
  r=new double [N+1];
  Radius(r);
  for (int i=1;i<=N;i++)
  v[i]=4*PI*r[i]*r[i]*r[i]/3;
  delete r;
}

void Sphere::SurfaceArea(double *a)
{
  double *r;
  r=new double [N+1];
  Radius(r);
  for (int i=1;i<=N;i++)
  a[i]=4*PI*r[i]*r[i];
  delete r;
}

void main()
{
  Sphere s;
  double *R,*A,*V;
  R=new double [N+1]; A=new double [N+1]; V=new double [N+1];
  s.Radius(R); s.Volume(V); s.SurfaceArea(A);
  for (int i=1;i<=N;i++)
  {
    cout << "data set " << i << ": radius=" << R[i] << endl;
    cout << "volume is " << A[i] << endl;
    cout << "surface area is " << V[i] << endl << endl;
  }
}

```

declaration of functions




```
C:\CNP2012\Code6\Debug\Code6.exe
data set 1: radius=1
volume is 12.568
surface area is 4.18933

data set 2: radius=2
volume is 50.272
surface area is 33.5147

data set 3: radius=3.16228
volume is 125.68
surface area is 132.478
```

6.7 Data Passing involving Structure

📌 Rules for data passing

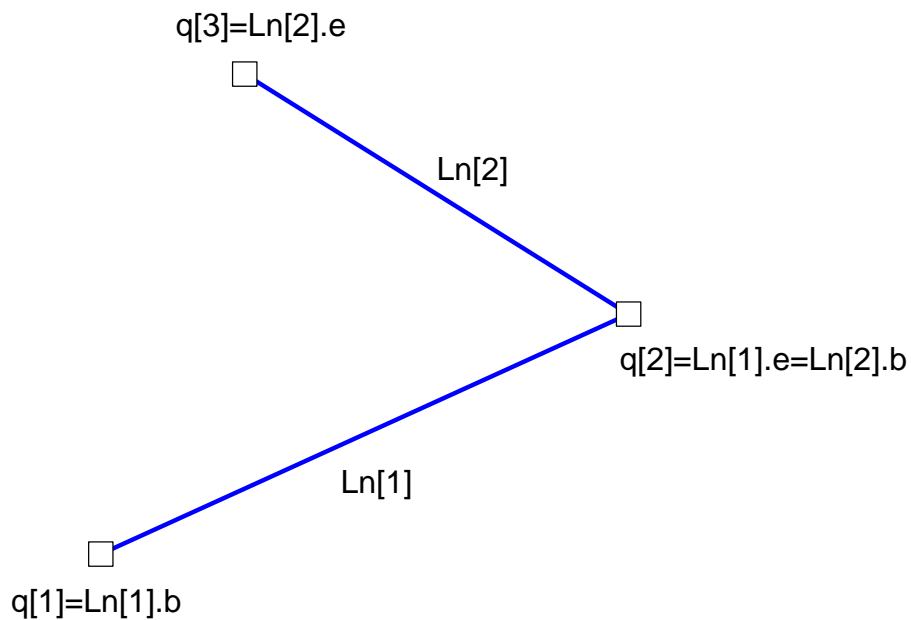
- both the passing and receiving functions must be declared with the same prototypes
- both the passing and receiving functions must match in their argument types and prototypes

POINT and LINE are structures.

L_n is a local object of LINE.

p , q , b and e are the objects of POINT.

Who are the members of POINT and LINE?



VC2010 Code6l.cpp: Class with structure.

```

typedef struct
{
    double x,y;
    char str[10];
} POINT;

typedef struct
{
    POINT b,e;
    double length;
} LINE;

class cg
{
public:
    cg()      { }
    void Compute(POINT *);
};

void cg::Compute(POINT *q)
{
    LINE *Ln;
    Ln=new LINE [n+1];
    for (int i=1;i<=n;i++)
        cout << q[i].str << ": (" << q[i].x << ", "
            << q[i].y << ")" << endl;

    Ln[1].b=q[1];
    Ln[1].e=q[2];
    Ln[2].b=q[2];
    Ln[2].e=q[3];
    for (i=1;i<=2;i++)
    {
        cout << "Ln " << i << ": (" << Ln[i].b.x
            << ", " << Ln[i].b.y << ") to (" << Ln[i].e.x
            << ", " << Ln[i].e.y << "), ";
        Ln[i].length=sqrt(pow(Ln[i].e.x-Ln[i].b.x,2)
            +pow(Ln[i].e.y-Ln[i].b.y,2));
        cout << "length is " << Ln[i].length << endl;
    }
    delete Ln;
}

void main()
{
    cg w;
    POINT *pt;
    pt=new POINT [n+1];
    pt[1].x=-2; pt[1].y=3; strcpy(pt[1].str,"Point 1");
    pt[2].x=1; pt[2].y=-1; strcpy(pt[2].str,"Point 2");
    pt[3].x=2; pt[3].y=5; strcpy(pt[3].str,"Point 3");
    w.Compute(pt);
    delete pt;
}
    
```

q values transferred to Ln[].b and Ln[].e

pt values assigned

6.8 Class Inheritance

- *Inheritance* refers to resources such as variables belonging to an earlier class which can be shared by newer classes.
- The earlier class is called the *base class*
- The newer classes are called *inherited classes*

Inheritance rules

- the inherited class can access any member of the base class, but not the other way around
- several levels of inheritance are supported in C++

VC2010 **Code6J.cpp:** Two classes collaborating.

```
#include <fstream>
#include <iostream>
#define N 6
using namespace std;

class A
{
public:
    A()                {}
    ~A()               {}
    void DataInput(int **);
};

void A::DataInput(int **p)
{
    ifstream InFile("Code6J.in");
    for (int i=1;i<=N;i++)
        for (int j=1;j<=i;j++)
            {
                InFile >> p[i][j];
                p[j][i]=p[i][j];
            }
}

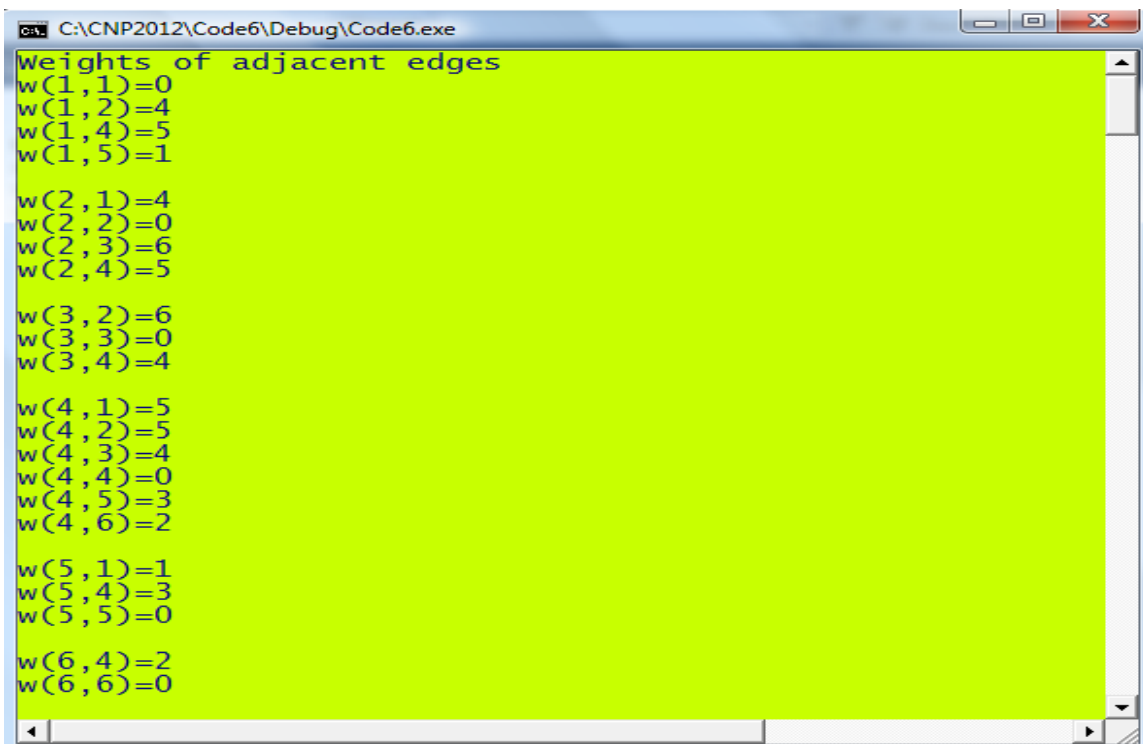
class B
{
public:
    B()                {}
    ~B()               {}
    void Adjacency();
};
```

```

void B::Adjacency()
{
    A g;
    int **q,i,j;
    q=new int *[N+1];
    for (i=1;i<=N;i++)
        q[i]=new int [N+1];
    g.DataInput(q);
    cout << "Weights of adjacent edges" << endl;
    for (i=1;i<=N;i++)
    {
        for (j=1;j<=N;j++)
            if (q[i][j]!=99)
                cout << "w(" << i << "," << j << ")="
                    << q[i][j] << endl;
        cout << endl;
    }
    delete q;
}

void main()
{
    B m;
    m.Adjacency();
    cin.get();
}

```



```

C:\CNP2012\Code6\Debug\Code6.exe
Weights of adjacent edges
w(1,1)=0
w(1,2)=4
w(1,4)=5
w(1,5)=1

w(2,1)=4
w(2,2)=0
w(2,3)=6
w(2,4)=5

w(3,2)=6
w(3,3)=0
w(3,4)=4

w(4,1)=5
w(4,2)=5
w(4,3)=4
w(4,4)=0
w(4,5)=3
w(4,6)=2

w(5,1)=1
w(5,4)=3
w(5,5)=0

w(6,4)=2
w(6,6)=0

```

base class

```

class A
{
public:
    A()    { }
    ~A()   { }
    void DataInput(int **);
};

void A::DataInput(int **p)
{
    ifstream InFile("Code6J.in");
    for (int i=1; i<=N; i++)
        for (int j=1; j<=i; j++)
            {
                InFile >> p[i][j];
                p[j][i]=p[i][j];
            }
    }
    
```

inherited class

B is inherited from A

```

class B: public A
{
public:
    B() { }
    ~B() { }
    void Adjacency();
};
    
```

VC2010 Code6K.cpp: Illustrating inheritance.

```

#include <fstream>
#include <iostream>
#define N 6
using namespace std;

class A
{
public:
    A()          { }
    ~A()         { }
    void DataInput(int **);
};

void A::DataInput(int **p)
{
    ifstream InFile("Code6J.in");
    for (int i=1;i<=N;i++)
        for (int j=1;j<=i;j++)
            {
                InFile >> p[i][j];
                p[j][i]=p[i][j];
            }
}

class B : public A
{
public:
    B()          { }
    ~B()         { }
    void Adjacency();
};

void B::Adjacency()
{
    int **q,i,j;
    q=new int *[N+1];
    for (i=1;i<=N;i++)
        q[i]=new int [N+1];
    DataInput(q);
    cout << "The adjacency matrix of G is given by: " <<endl;
    for (i=1;i<=N;i++)
    {
        for (j=1;j<=N;j++)
            cout << ((q[i][j]==99)?0:1) << " ";
        cout << endl;
    }
    cout <<endl;
    delete q;
}

void main()
{
    B m;
    m.Adjacency();
    cin.get();
}

```

}

```
C:\CNP2012\Code6\Debug\Code6.exe
The adjacency matrix of G is given by:
1 1 0 1 1 0
1 1 1 1 0 0
0 1 1 1 0 0
1 1 1 1 1 1
1 0 0 1 1 0
0 0 0 1 0 1
```


Polymorphism

- 2 or more functions using the same name which exist in two or more classes, including the base and derived classes
- For these 2 functions, a function from the base class is called by default whenever it is called (refer to Code6L.cpp)
- To override the function from the base class, always declare the function in the base class as **virtual** (refer to Code6M.cpp)

Code6L.cpp: without virtual functions

```

class A
{
public:
    double f(double x);
    double g(double x);
};

double A::f(double x)
{
    return x*x;
}

double A::g(double x)
{
    return f(x);
}

class B : public A
{
public:
    double f(double x);
};

double B::f(double x)
{
    return x*x*x;
}

void main()
{
    B m;
    cout << "the returned value is " << m.g(3) << endl;
}
    
```

final output:
3*3=9

ignored

Code6M.cpp: with virtual functions

```

#include <iostream.h>

class A
{
public:
    virtual double f(double x);
    double g(double x);
};

double A::f(double x)
{
    return x*x;
}

double A::g(double x)
{
    return f(x);
}

class B:public A
{
public:
    double f(double x);
};

double B::f(double x)
{
    return x*x*x;
}

void main()
{
    B m;
    cout << "the returned value is " << m.g(3) << endl;
}
    
```

