

# SKF 3143

## Process Control and Dynamics: Control of Chemical Processes

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# Learning Objectives

**When I complete this chapter, I want to be able to do the following:**

1. identify main control variables and their application
2. classify type of variables in chemical processes

# Outline of this lecture

-  **1** Typical Control Variables .....
-  **2** Common Unit Operations .....
-  **3** Classification of Variables .....



Chemical process variables.

Typical control variables.

# TYPICAL CONTROL VARIABLES



# Chemical process variables.

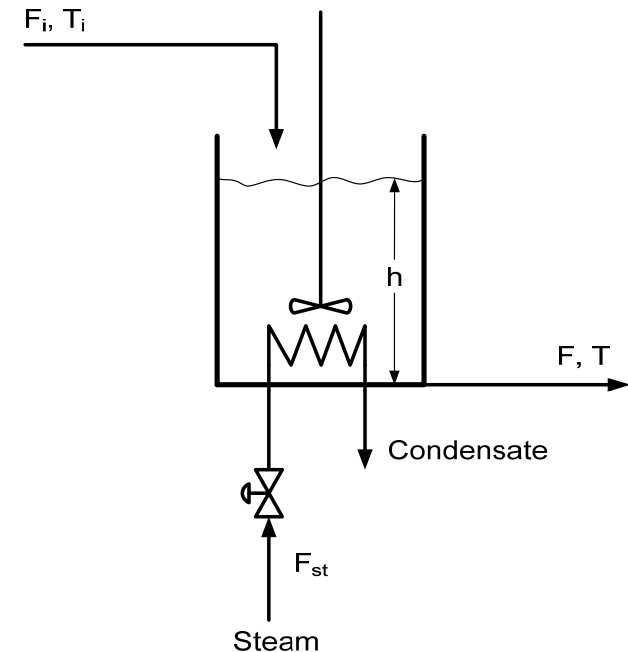
- Variables such as flow rates, temperatures, pressures, volumes, pHs, viscosities and concentrations can be divided in to two groups
  - Input Variables: Effect of surroundings on the chemical process
  - Output Variables: Effect of chemical process on the surroundings
- Input Variables:  $F_i$ ,  $T_i$ ,  $F_{st}$ , ( $F$ )
- Output Variables:  $F$ ,  $V$  or  $h$ ,  $T$

## Input Variable

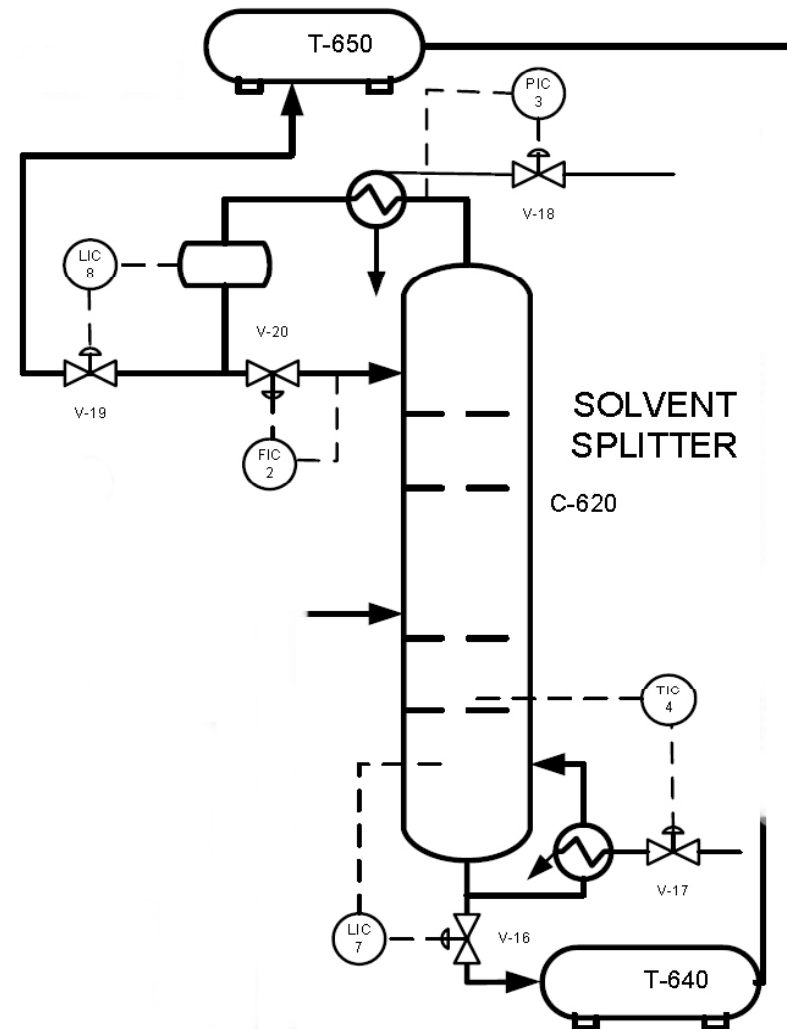
- Manipulated: their values can be adjusted freely by control mechanism ( $F_{st}$  and  $F$ )
- Disturbances: values are not the result of adjustment by control mechanism ( $F_i$  and  $T_i$ )

## Output Variable

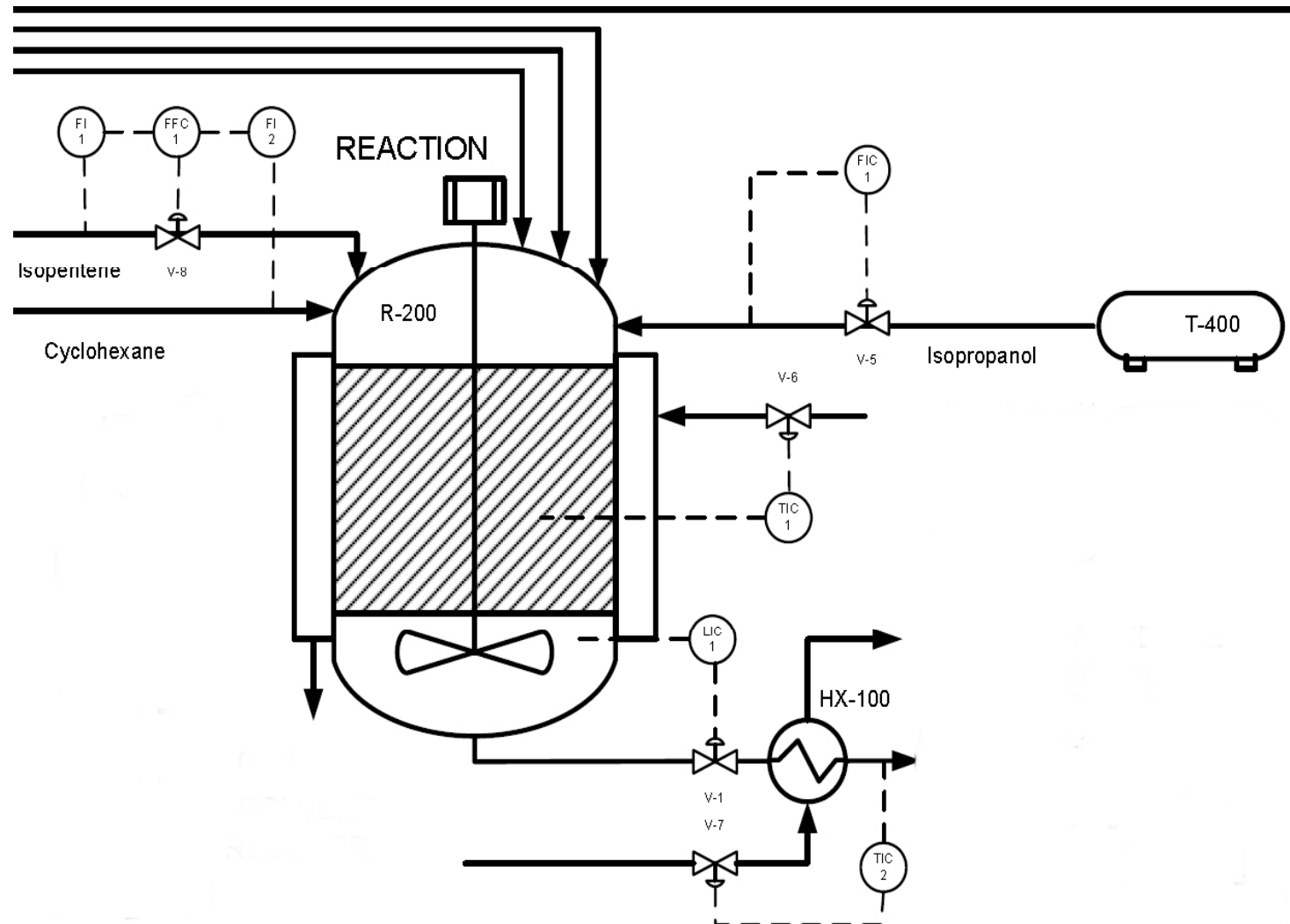
- Measured: values are known by directly measuring them ( $V$  and  $T$ )
- Unmeasured: cannot be measured directly



# Exercise: Typical control variables for Solvent Splitter.



# Exercise: Typical control variables for Polymerization Reactor.





Some typical continuous processes.

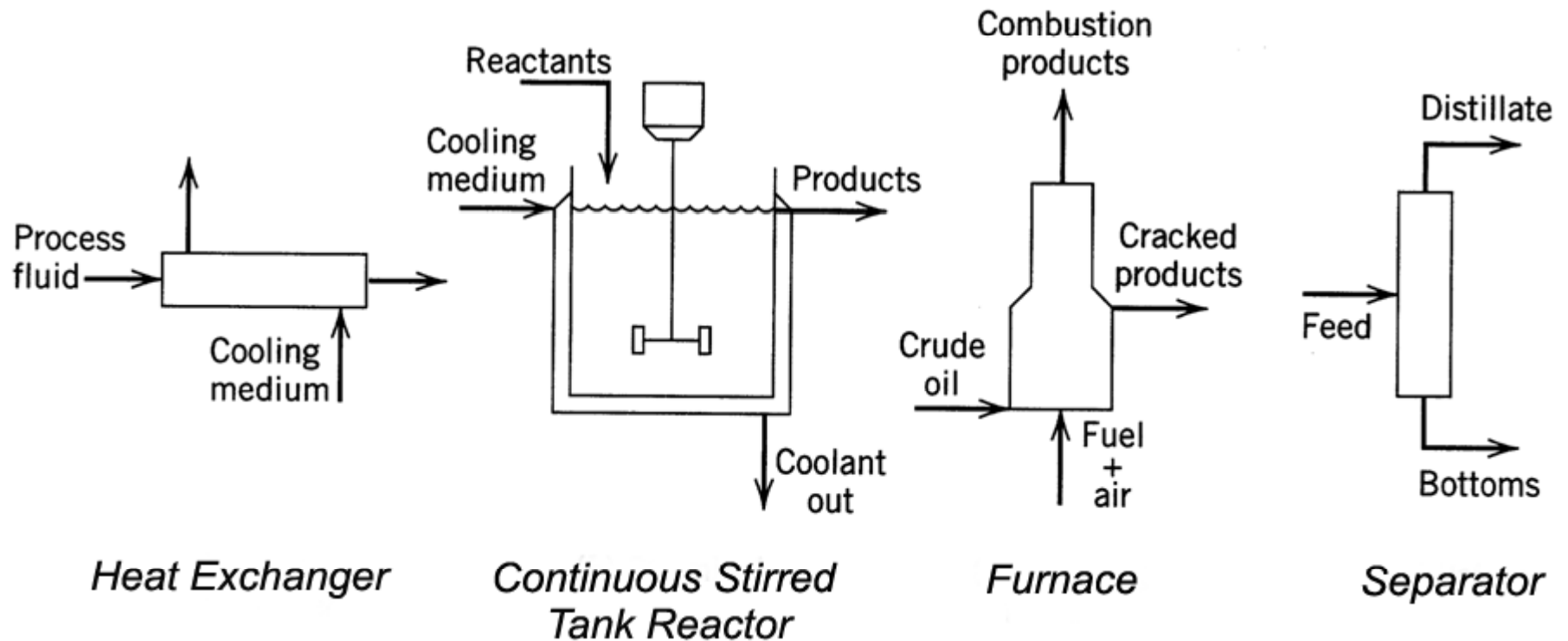
Some typical noncontinuous processes.

# COMMON UNIT OPERATIONS

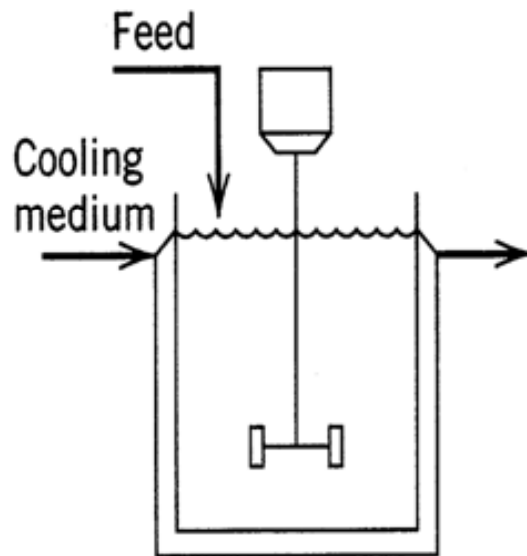




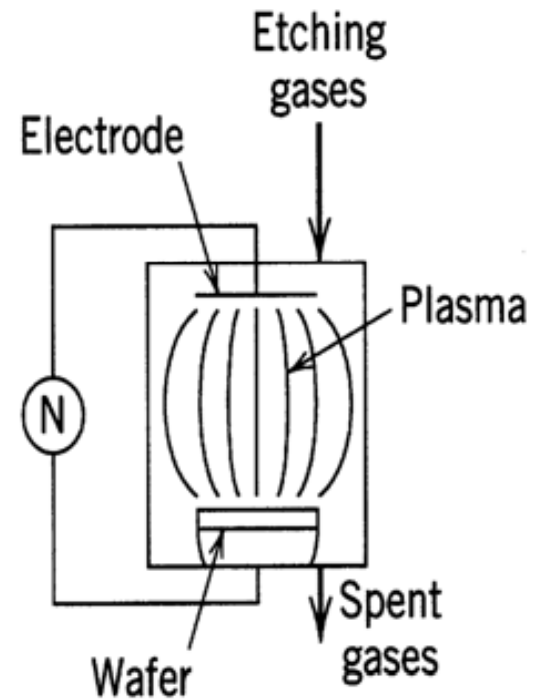
# Some typical continuous processes.



# Some typical noncontinuous processes.



*Semi Batch Reactor*



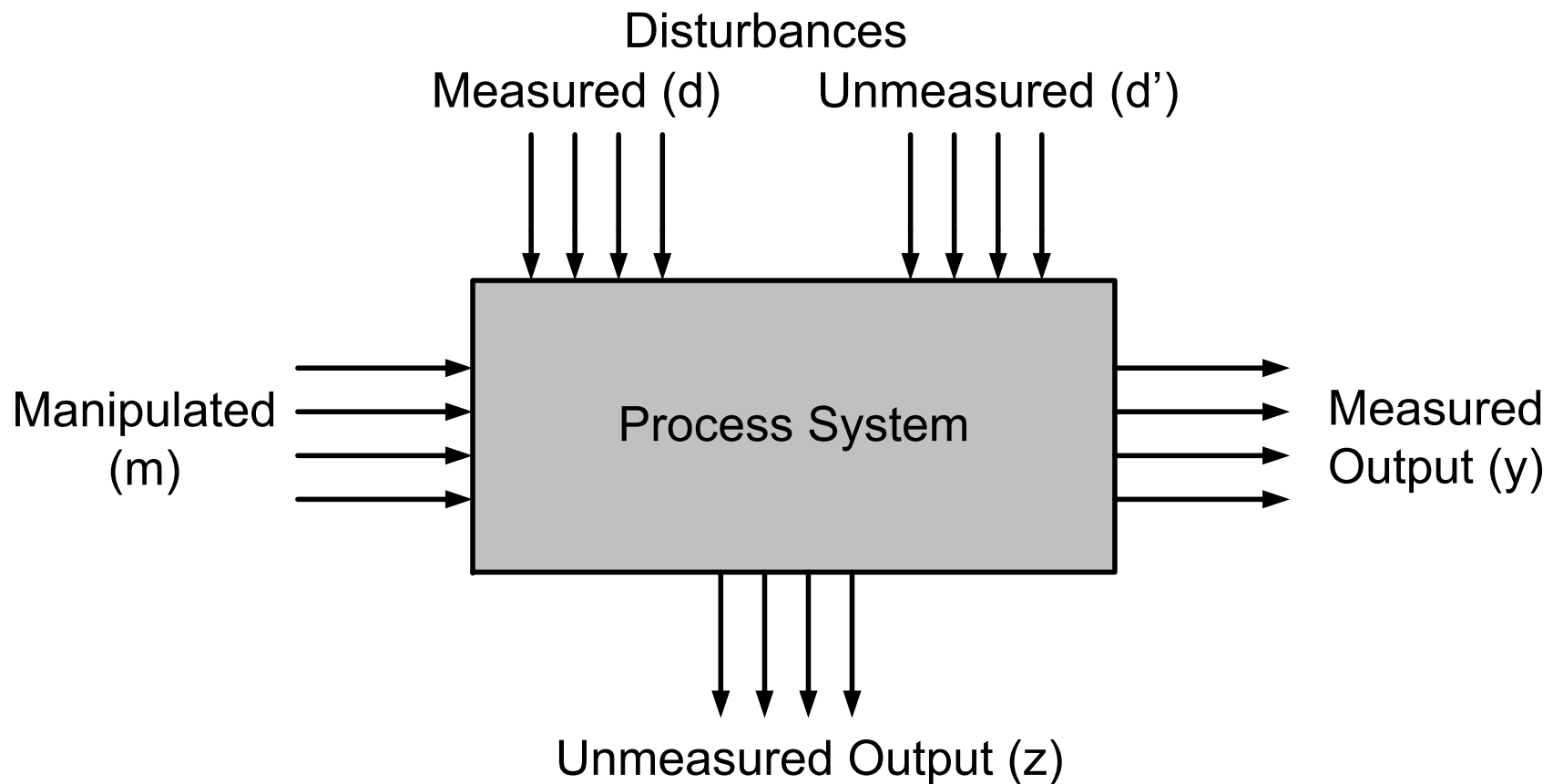
*Plasma Etcher*

- Chemical process variables.
- Design elements of control system.
- Selecting measurements.
- Selecting manipulated variables.
- Selecting controller configuration

## CLASSIFICATION OF VARIABLES



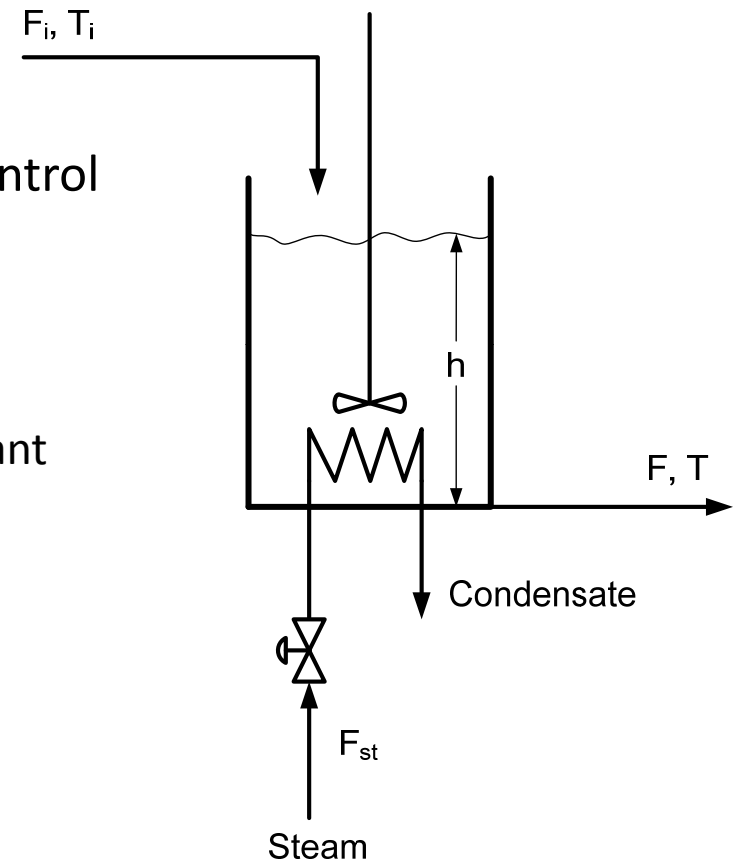
# Chemical process variables.



# Design elements of control system.

## Define control objectives

- What are the operational objectives that a control system is called upon to achieve
  - Ensuring the stability of the process
  - Suppressing the external disturbances
  - Optimising the economic performance of a plant
  - A combination of the above
- For the example, the control objectives
  - To control the temperature and volume
  - $T = T_s$
  - $V = V_s$
  - Where  $T_s$  and  $V_s$  are the desired values

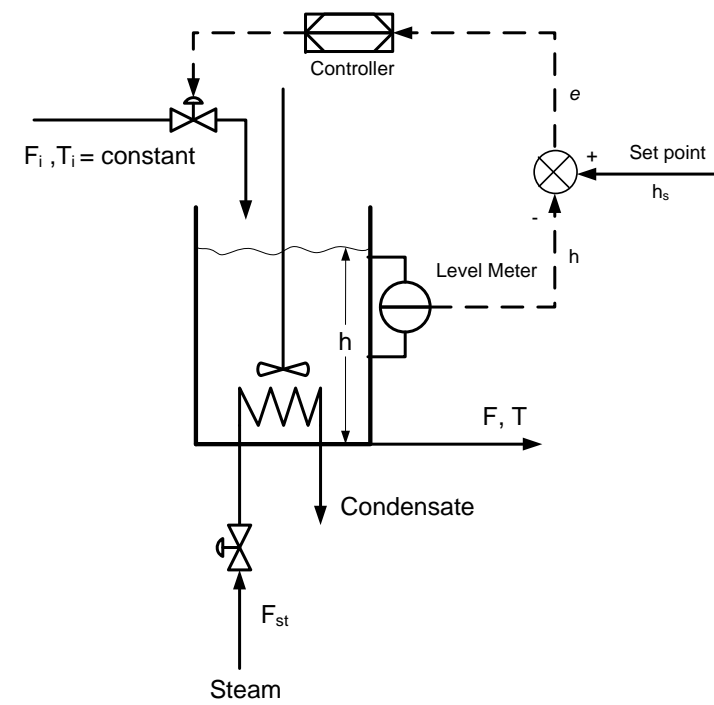
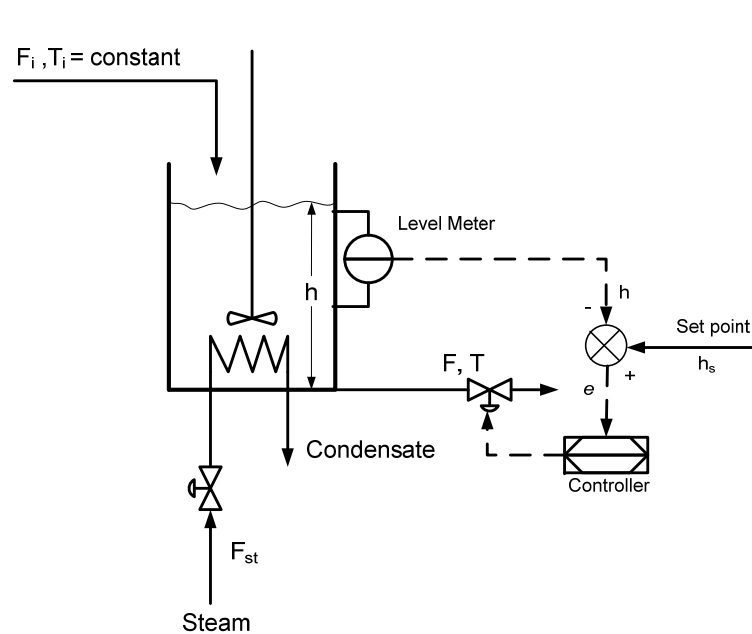


# Selecting measurements.

- Selecting measurement
  - We need some means to monitor the performance of the chemical process
  - This is done by measuring the values of certain processing variables (temperature, pressures, concentration, flow rates, pH)
- What variables should we measure in order to monitor the operational performance of a plant?
  - For tank heating system our control objectives are to keep the volume and temperature at desired value
  - Thus we have to measure
    - Temperature (T) using thermocouple
    - Volume (V) using Differential Pressure Cell (DPC)

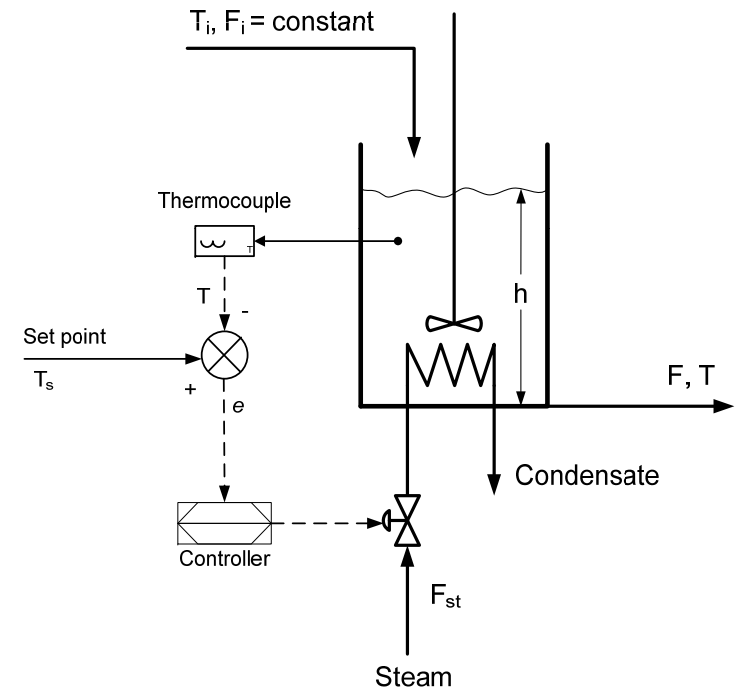
# Selecting manipulated variables.

- What are the manipulated variables to be used to control a chemical process?
  - Usually we have several options to choose ( $F_i$  or  $F$ )
  - The selection is very crucial because it will affect the quality of the control action



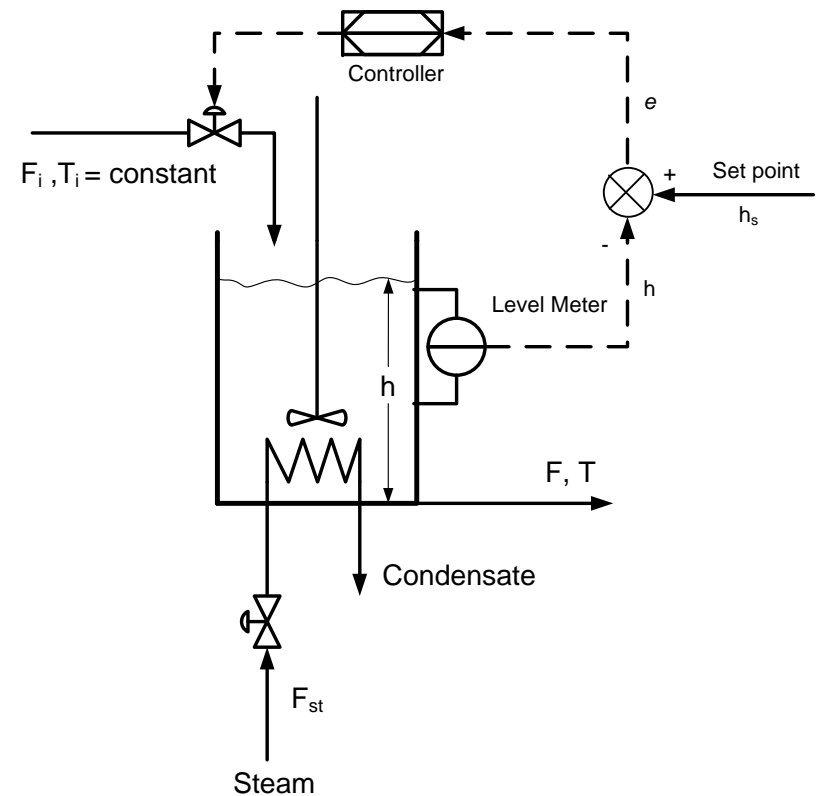
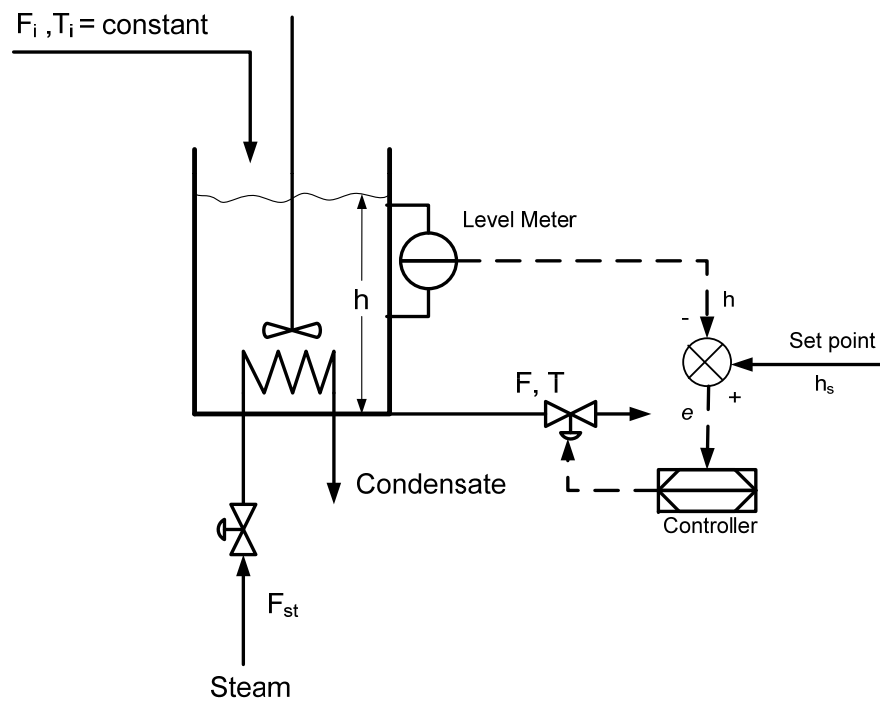
# Selecting controller configuration

- Feedback control constitute two different control configuration:
  - Same information flows to different manipulated variables
  - Same manipulated variables but different measurement
- Control Structure
  - Information structure that is used to connect the available measurements to the available manipulated variables





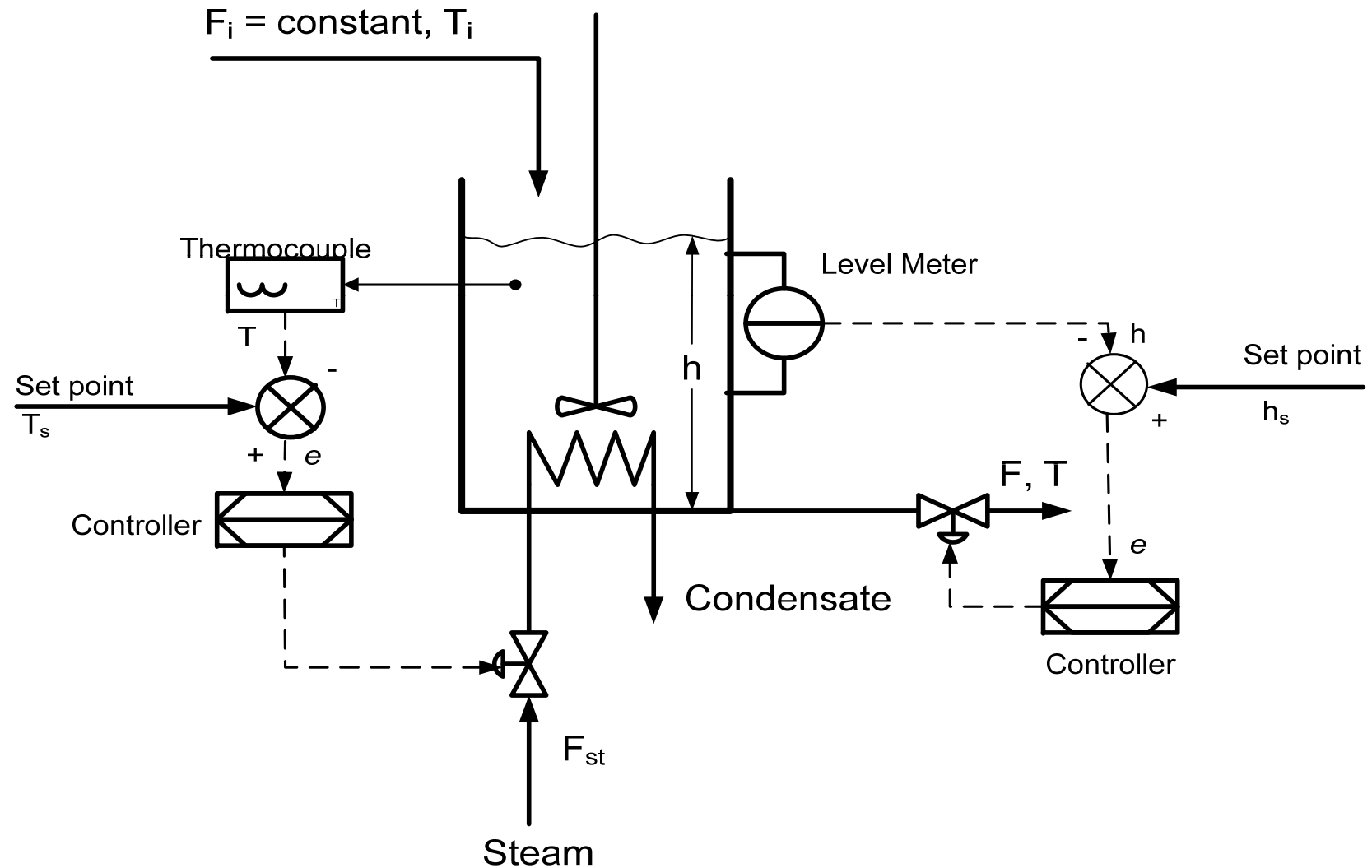
Same information but different manipulated variables.



# Controller configuration.

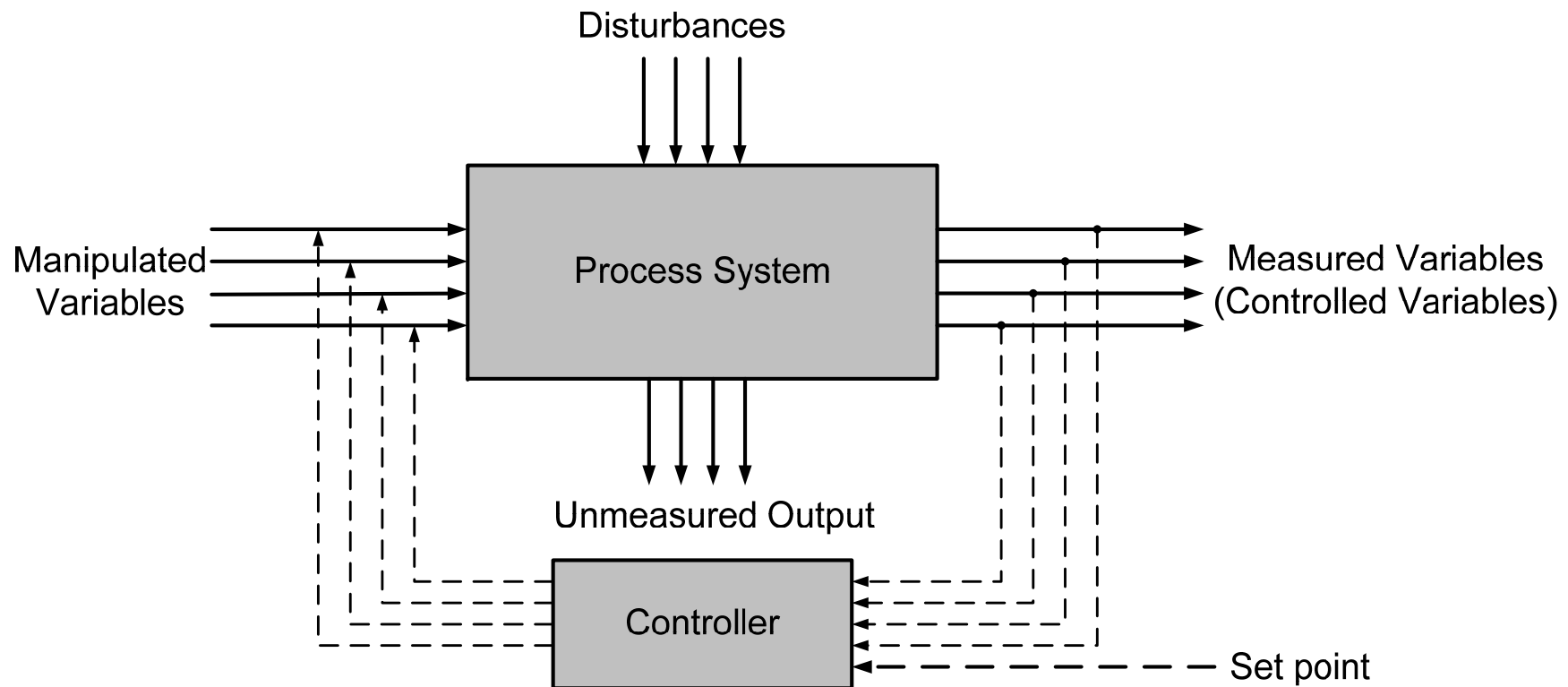
- What is the best control configuration for a given process control situation?
  - The answer for this is very critical for the quality of the control system we are to design
- Controller Configuration
  - SISO – single input single output
  - MIMO – multiple input multiple output
- For heated tank system
  - If the control objectives is to keep the level at a desired value by manipulating the effluent flow rate, we have a SISO system
  - If the control objectives are to control level and temperature, we have MIMO system.

# MIMO controller.

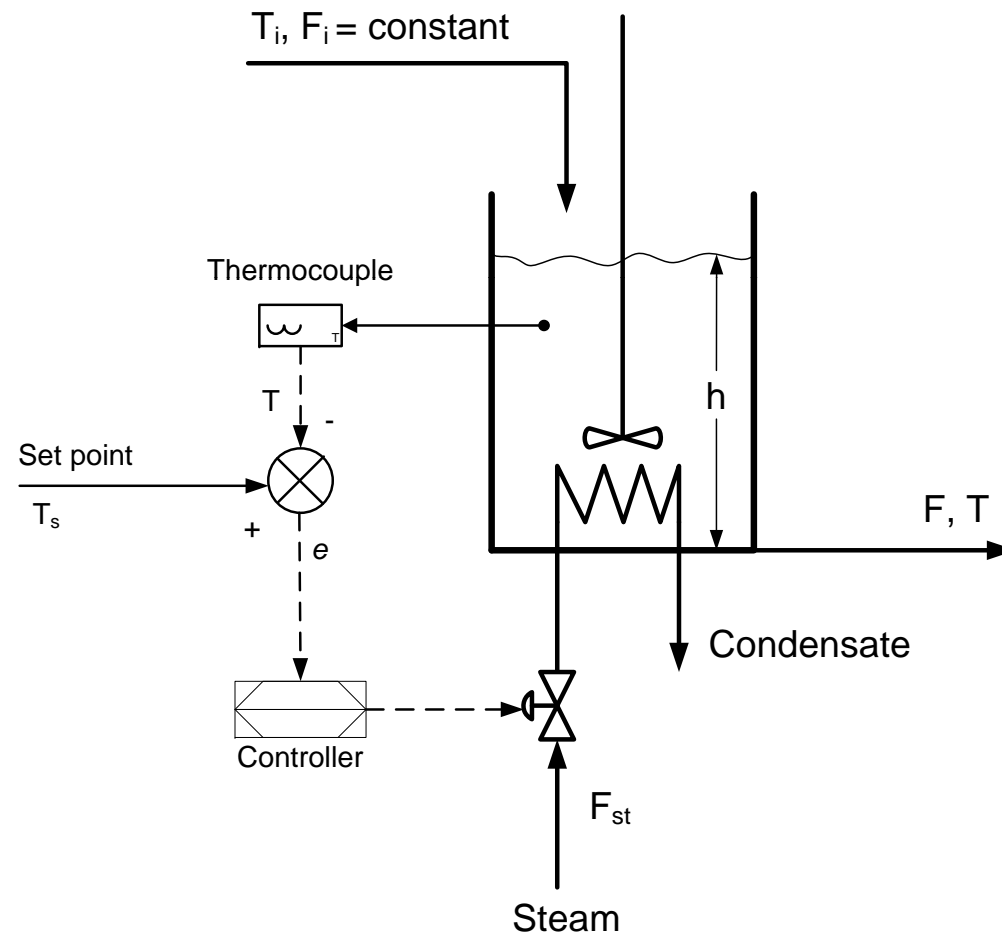


# Feedback Controller

- Uses direct measurements of the controlled variables to adjust the values of the manipulated variables
- Objectives: to keep the controlled variables at desired levels (set points)

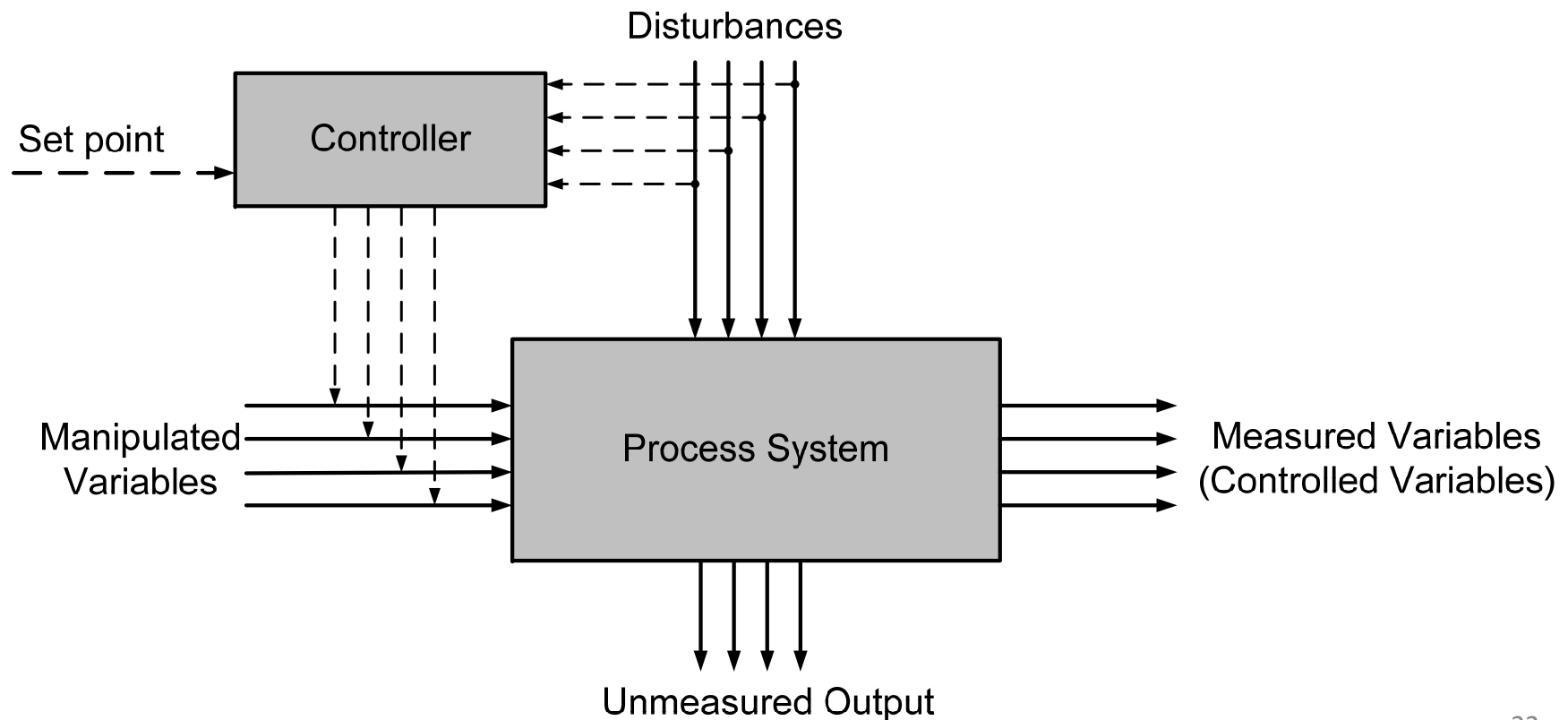


# Feedback Control for Temperature

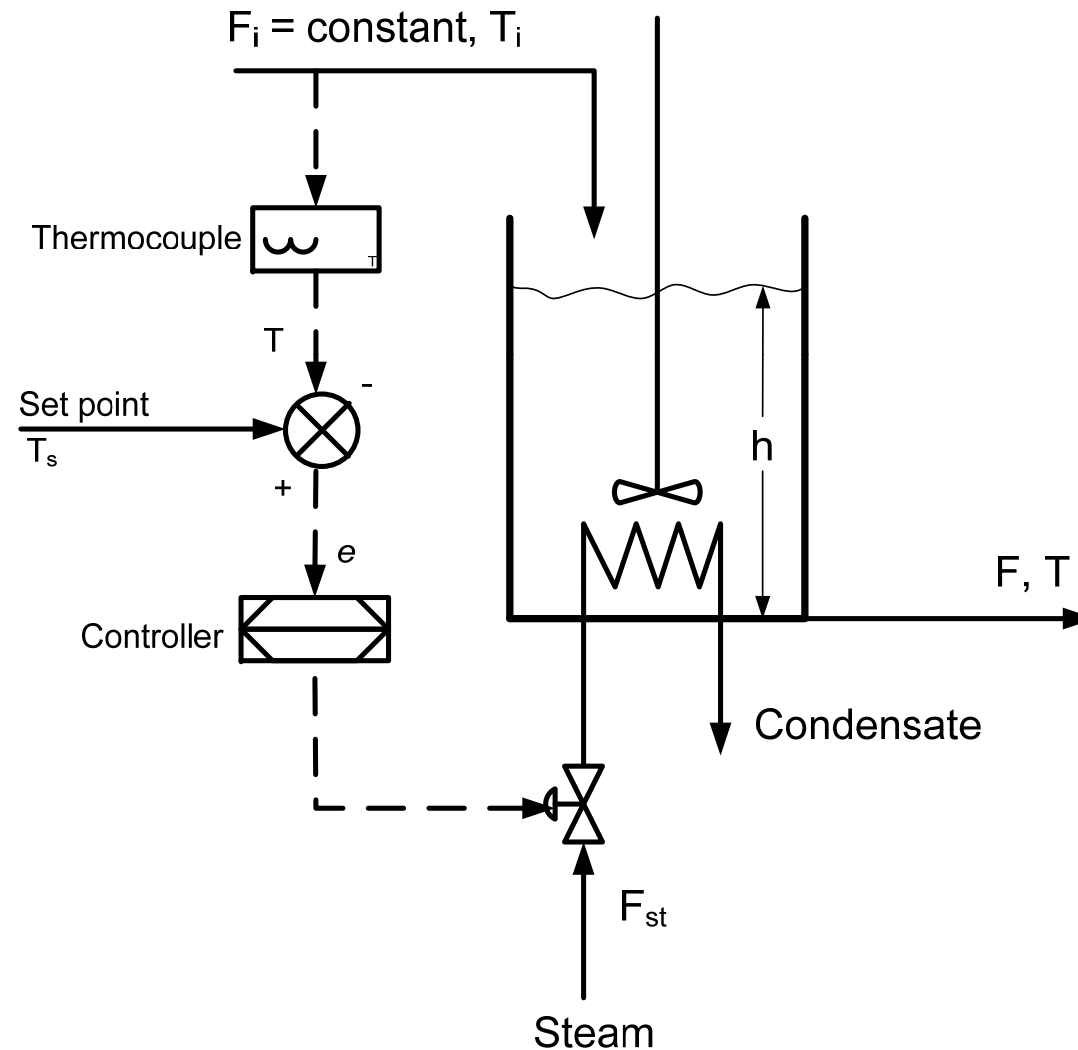


# Feedforward Controller

- Uses direct measurement of the disturbances to adjust manipulated variables
- The objective here is to keep the values of the controlled output variables at desired levels

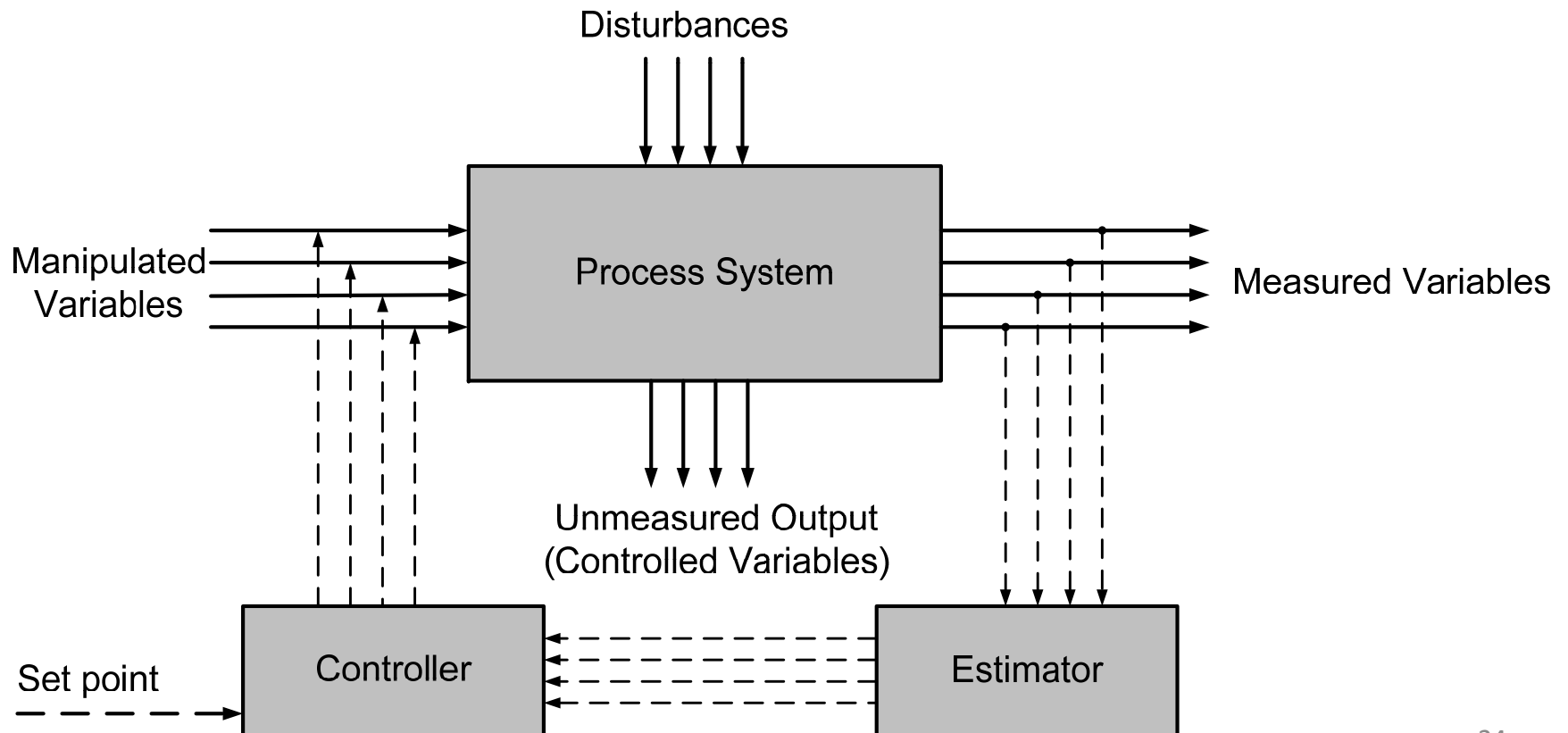


# Feedforward Controller for Temperature



# Inferential Controller Configuration

- Uses secondary measurements to adjust the manipulated variables because the controlled variables cannot be measured
- Control objective here is to keep the unmeasured controlled variables at desired levels





## References:

- Seborg, D. E., Edgar, T. F., Mellinchamp, D. A. (2003). *Process Dynamics and Control*, 2<sup>nd</sup>. Edition. John Wiley, ISBN: 978-04-71000-77-8.
- Marlin, T. E. (2000). *Process Control: Designing Processes and Control System for Dynamic Performance*, 2<sup>nd</sup>. Edition. McGraw Hill, ISBN: 978-00-70393-62-2.
- Stephanopoulos, G. (1984). *Chemical Process Control. An Introduction to Theory and Practice*. Prentice Hall, ISBN: 978-01-31286-29-0