COMPUTATIONAL PHYSICS (SSP2122)

Restoring Force

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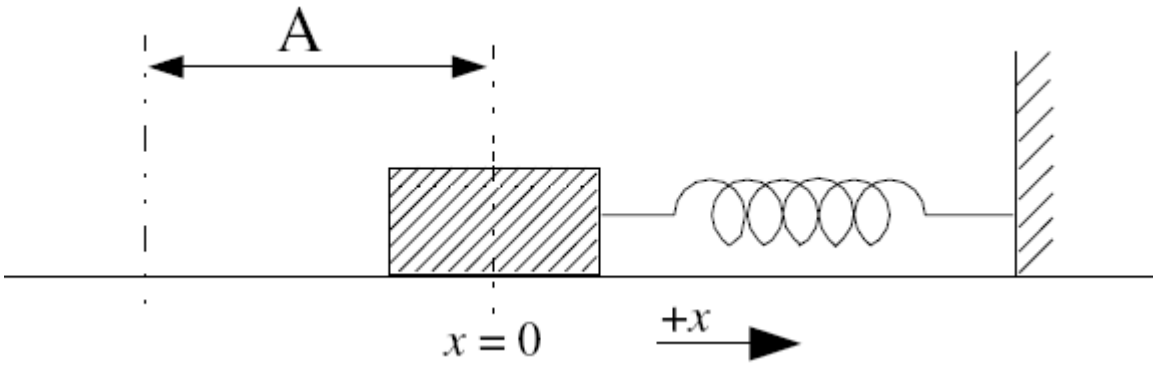
Damped Harmonic Oscillation



Object *m* is on a flat surface attached to a spring as in figure above. The object is pulled to position A, and released so that it oscillates about *x*=0. Assuming that the force *F =ma= -bv-kx*, where *x* is position of the object, *v* is the velocity, *k* the spring constant, and *b* is a constant associated with friction with the flat surface.

The algorithm :

1. Declare the class/method to be used
2. Declare and assign all variables to be used;
   x, t, delt, k, b, A, m, F, a, v, v0 and x0;
3. Declare and assign constants to the respective variables;
   k = 0.2, b = 0.1, A = 0.1, m = 0.5;
4. Select appropriate value for Δt
5. Initialized initial values; x_o=A, v_o=0.0
6. set $x=x_o$, $v=v_o$, and t = 0;
7. calculate the value of force; F = -kx-bv
8. calculate the value of acceleration; a = F/m
9. calculate velocity; $v = v_o + \Delta v = v_o + a\,\Delta t$
10. calculate position; $x = x_o + \Delta x = x_o + v\,\Delta t$
11. increment value of t by Δt
12. print out values of t and x
13. swap the value of: x_o=x, v_o=v
14. repeat from step 4 until stopping condition is satisfied (t<=60.0)

The java code:

```
public class simplehar01
{
  public static void main(String args[])
  {
   double x, t, delt;
   double k, b, A, m, F, a, v, v0, x0;
   k = 0.2;
   b = 0.1;
   A = 0.1;
```

```
    m = 0.5;
    delt = 0.001;
    v0 = 0.0;
    x0 = A;
    x = x0; v = v0;
    t = 0.0;
      while(t<=60.0)
            {
            F = -k*x-b*v;
            a = F/m;
            v = v0 + a*delt;
            x = x0 + v*delt;
            t = t + delt;
            System.out.printf("%f %f\n",t,x);
            x0 = x;
            v0 = v;
            }
    }
}
```

gnuplot result: