

# SET 4573: Data Communication and Switching System

## Chapter 3: Data Communication Basic

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# Asynchronous and Synchronous Transmission

- Synchronization is to synchronize the transmitter and receiver
  - receiver samples data stream at bit intervals
  - the clocks has to be aligned so that the sampling is done at the correct time
- Two solutions to synchronizing clocks
  - asynchronous transmission
  - synchronous transmission

# Asynchronous Transmission

- Simple and cheap method of transmission
- Every character is sent with overhead of 2 or 3 bits (start, parity and stop bit)
- ~20% loss due to overhead



# Synchronous Transmission

- block of data transmitted sent as a frame/packet
- clocks must be synchronized
  - using separate clock line or
  - embedded clock signal in the data sent
- indication for the start and end of block
  - use preamble and postamble (flag and control fields)
- more efficient (lower overhead) than asynchronous transmission



# Error in Transmission

- an error occurs when a bit is altered between transmission and reception process
  - e.g. from '1' to '0' or vice versa
- single bit errors
  - only one bit altered
- burst errors
  - sequence of several bits in error
  - mostly occur at higher data rates

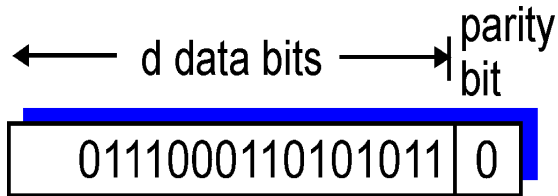
# Error Detection

- detect using error-detecting code
- added by transmitter
- recalculated and checked by receiver
- example
  - parity
    - parity bit is set so character has even (even parity) or odd (odd parity) number of '1'
    - even number of bit errors cannot be detected
  - Cyclic Redundancy Check (CRC)
    - check a block number of bits

# Parity Checking

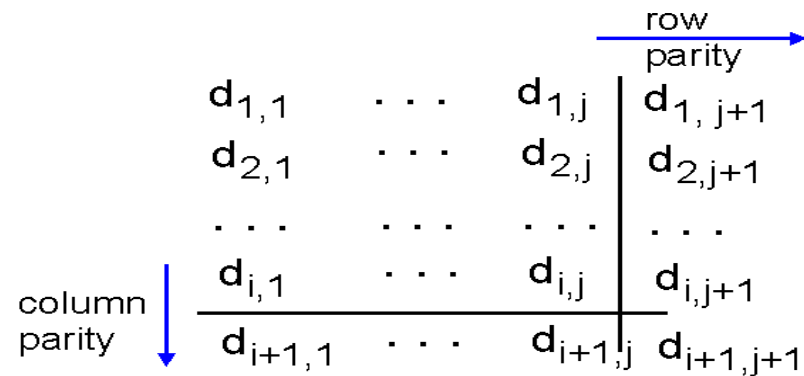
## Single bit parity:

Detect single bit error



## Two Dimensional Bit Parity:

Detect & correct single bit error



1	0	1	0	1	1
1	1	1	1	0	0
0	1	1	1	0	1
<hr/>					
1	0	1	0	1	0

*no errors*

1	0	1	0	1	1
1	1	1	0	0	0
0	1	1	1	0	1
<hr/>					
1	0	1	0	1	0

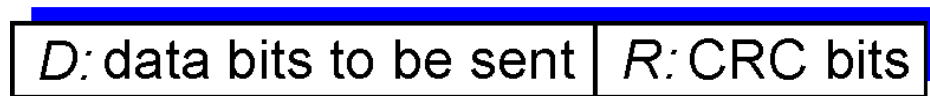
parity error

*correctable  
single bit error*

# Cyclic Redundancy Check

- for a block of  $d$  bits, transmitter generates an  $r$  bit of CRC bit
- transmits  $(d+r)$  bits which is exactly divisible by a pre-determined number,  $G$  ( $r+1$  bits)
- receiver divides the frame by  $G$  (modulo 2)
  - if no remainder, no error detected

←  $d$  bits → ←  $r$  bits →



*bit  
pattern*

$$D * 2^r \text{ XOR } R$$

*mathematical  
formula*

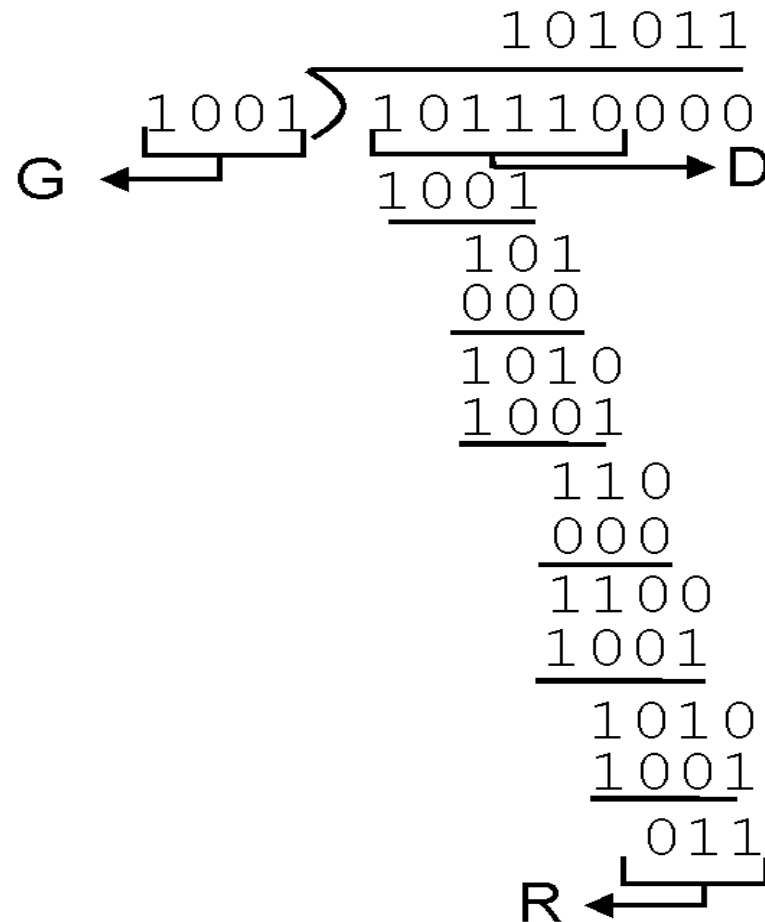


# CRC Example

Divide  $D \cdot 2^r$  by  $G$  using modulo-2

Add the remainder  $R$  to the end of the bits

$$R = \text{remainder}\left[\frac{D \cdot 2^r}{G}\right]$$



# Error Control

- Detection and correction of errors
- 2 types of 'error'
  - lost frames
  - damaged frames
- Error correction
  - positive/negative acknowledgment
  - retransmission
    - after timeout
    - if negative acknowledgement

# Flow Control techniques

- Stop and Wait
- Sliding Window
  - Go-back-N
  - Selective Reject

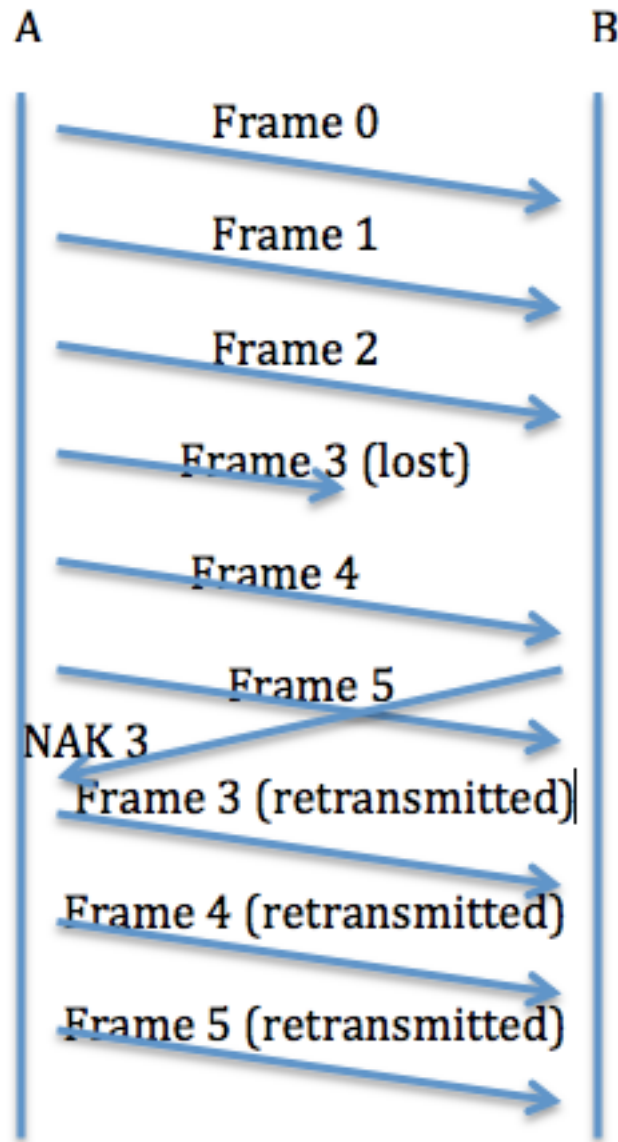
# Stop and Wait

- Source transmits single frame/packet
  - wait for ACK for the frame sent
  - if ACK frame received correctly, send the next frame
  - if negative ACK frame is received, retransmit the sent frame
  - if no ACK frame received within timeout, retransmit the sent frame

# Go-Back-N

- Works based on sliding window
  - send multiple number of frame simultaneously
  - the number of frames that can be sent depends on window size
  - one ACK frame can acknowledge a number of frames sent
- If negative ACK is received for a frame
  - retransmit the 'error frame(s)' and all subsequent frame(s) that have been sent

# Go-Back-N Diagram



# Selective Reject

- Almost the same with go-back-N
  - only rejected (error) frames are retransmitted
  - subsequent frames are accepted by the receiver and buffered and will not be retransmitted
- Minimizes retransmission
  - retransmit only the 'error/corrupted frame(s)'
- Receiver must maintain large enough buffer to store already sent frame(s)

# Selective Reject-Diagram

